Synchronous Languages—Lecture 18

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Lustre

Slide 1

Overview

A Short Tour

Examples

Clock Consistency

Arrays and Recursive Nodes

Lustre

- ► A synchronous data flow language
- ▶ Developed since 1984 at IMAG, Grenoble [HCRP91]
- Also graphical design entry available (SAGA)
- Moreover, the basis for SCADE, a tool used in software development for avionics and automotive industries
- → Translatable to FSMs with finitely many control states
- ► Same advantages as Esterel for hardware and software design

Lustre Modules

General form:

```
node f(x_1:\alpha_1, \ldots, x_n:\alpha_n) returns (y_1:\beta_1, \ldots, y_m:\beta_m) var z_1:\gamma_1, \ldots, z_k:\gamma_k;

let z_1 = \tau_1; \ldots; z_k = \tau_k; y_1 = \pi_1; \ldots; y_m = \pi_k; assert \varphi_1; \ldots; assert \varphi_\ell; tel
```

where

- f is the name of the module
- Inputs x_i, outputs y_i, and local variables z_j
- ightharpoonup Assertions φ_i (boolean expressions)

Lustre Programs

- Lustre programs are a list of modules that are called nodes
- All nodes work synchronously, i. e. at the same speed
- ▶ Nodes communicate only via inputs and outputs
- ▶ No broadcasting of signals, no side effects
- **Equations** $z_i = \tau_i$ and $y_i = \pi_i$ are not assignments
- Equations must have solutions in the mathematical sense

Lustre Programs

- As $z_i = \tau_i$ and $y_i = \pi_i$ are equations, we have the Substitution Principle:
 - The definitions $z_i = \tau_i$ and $y_i = \pi_i$ of a Lustre node allow one to replace z_i by τ_i and y_i by π_i .
- ▶ Behavior of z_i and y_i completely given by equations $z_i = \tau_i$ and $y_i = \pi_i$

Assertions

- Assertions assert φ do not influence the behavior of the system
- lacktriangle assert φ means that during execution, φ must invariantly hold
- Equation X = E equivalent to assertion assert(X = E)
- Assertions can be used to optimize the code generation
- Assertions can be used for simulation and verification

Data Streams

- All variables, constants, and all expressions are streams
- Streams can be composed to new streams
- Example: given x = (0, 1, 2, 3, 4, ...) and y = (0, 2, 4, 6, 8, ...), then x + y is the stream (0, 3, 6, 9, 12, ...)
- ► However, streams may refer to different clocks
- → Each stream has a corresponding clock

Data Types

- Primitive data types: bool, int, real
 - Semantics is clear?
- ightharpoonup Imported data types: type α
 - Similar to Esterel
 - Data type is implemented in host language
- ▶ Tuples of types: $\alpha_1 \times ... \times \alpha_n$ is a type
 - Semantics is Cartesian product

Expressions (Streams)

- Every declared variable x is an expression
- Boolean expressions:
 - ightharpoonup au_1 and au_2 , au_1 or au_2 , not au_1
- ► Numeric expressions:
 - ightharpoonup $au_1+ au_2$ and $au_1- au_2$, $au_1* au_2$ and au_1/ au_2 , au_1 div au_2 and au_1 mod au_2
- Relational expressions:
 - $\tau_1 = \tau_2, \ \tau_1 < \tau_2, \ \tau_1 \le \tau_2, \ \tau_1 > \tau_2, \ \tau_1 \ge \tau_2$
- Conditional expressions:
 - ▶ if b then τ_1 else τ_2 for all types

Node Expansion

- Assume implementation of a node f with inputs $x_1 : \alpha_1, \ldots, x_n : \alpha_n$ and outputs $y_1 : \beta_1, \ldots, y_m : \beta_m$
- ▶ Then, f can be used to create new stream expressions, e.g., $f(\tau_1, \ldots, \tau_n)$ is an expression
 - ightharpoonup Of type $\beta_1 \times \ldots \times \beta_m$
 - ▶ If (τ_1, \ldots, τ_n) has type $\alpha_1 \times \ldots \times \alpha_n$

Vector Notation of Nodes

By using tuple types for inputs, outputs, and local streams, we may consider just nodes like

```
node f(x:\alpha) returns (y:\beta)

var z:\gamma;

let

z = \tau;

y = \pi;

assert \varphi;

tel
```

Clock-Operators

- ► All expressions are streams
- Clock-operators modify the temporal arrangement of streams
- Again, their results are streams
- ► The following clock operators are available:
 - ightharpoonup pre au for every stream au
 - $au_1 o au_2$, (pronounced "followed by") where au_1 and au_2 have the same type
 - $ightharpoonup au_1$ when au_2 where au_2 has boolean type (downsampling)
 - ightharpoonup current au (upsampling)

- As already mentioned, streams may refer to different clocks
- ▶ We associate with every expression a list of clocks
- ightharpoonup A clock is thereby a stream φ of boolean type

ightharpoonup clocks(au):=[] for expressions without clock operators

- ightharpoonup clocks $(\tau) := []$ for expressions without clock operators
- ightharpoonup clocks(au) := clocks(au)

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- ightharpoonup clocks(pre(au)) := clocks(au)
- ► clocks $(\tau_1 \rightarrow \tau_2) := \text{clocks}(\tau_1)$, where clocks $(\tau_1) = \text{clocks}(\tau_2)$ is required

- ightharpoonup clocks(au) := [] for expressions without clock operators
- ightharpoonup clocks(pre(au)) := clocks(au)
- ► clocks(τ_1 -> τ_2) := clocks(τ_1), where clocks(τ_1) = clocks(τ_2) is required
- ▶ clocks(τ when φ) := [φ , c_1 , ..., c_n], where clocks(φ) = clocks(τ) = [c_1 , ..., c_n]

- ightharpoonup clocks(au) := [] for expressions without clock operators
- ightharpoonup clocks(pre(au)) := clocks(au)
- ► clocks(τ_1 -> τ_2) := clocks(τ_1), where clocks(τ_1) = clocks(τ_2) is required
- ▶ clocks(τ when φ) := [φ , c_1 , ..., c_n], where clocks(φ) = clocks(τ) = [c_1 , ..., c_n]
- ▶ clocks(current(τ)) := [c_2, \ldots, c_n], where clocks(τ) = [c_1, \ldots, c_n]

$$ightharpoonup \llbracket \operatorname{pre}(au)
rbracket := (oldsymbol{\perp}, au_0, au_1, \ldots)$$
, provided that $\llbracket au
rbracket = (au_0, au_1, \ldots)$

```
ightharpoonup \llbracket \operatorname{pre}(	au) 
rbracket := (\bot, 	au_0, 	au_1, \ldots), \text{ provided that } \llbracket 	au 
rbracket = (	au_0, 	au_1, \ldots)
```

- $ightharpoonup \llbracket \operatorname{pre}(au)
 rbracket := (ot, au_0, au_1, \ldots)$, provided that $\llbracket au
 rbracket = (au_0, au_1, \ldots)$
- $\llbracket \tau \text{ when } \varphi \rrbracket = (\tau_{t_0}, \tau_{t_1}, \tau_{t_2}, \ldots)$, provided that
 - $ightharpoonup [\![\tau]\!] = (\tau_0, \tau_1, \ldots)$
 - $\{t_0, t_1, \ldots\}$ is the set of points in time where $[\![\varphi]\!]$ holds

- lacksquare $\llbracket \mathtt{pre}(au)
 rbracket := (ot, au_0, au_1, \ldots)$, provided that $\llbracket au
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 - $ightharpoonup [\![\tau]\!] = (\tau_0, \tau_1, \ldots)$
 - $\{t_0, t_1, \ldots\}$ is the set of points in time where $[\![\varphi]\!]$ holds
- $[[\operatorname{current}(\tau)]] = (\bot, \ldots, \bot, \tau_{t_0}, \ldots, \tau_{t_0}, \tau_{t_1}, \ldots, \tau_{t_1}, \tau_{t_2}, \ldots),$ provided that
 - $\blacktriangleright \llbracket \tau \rrbracket = (\tau_0, \tau_1, \ldots)$
 - $\{t_0, t_1, \ldots\}$ is the set of points in time where the highest clock of current (τ) holds

CALU

φ	0	1	0	1	0	0	1
au	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{ extsf{4}}$	$ au_{5}$	$ au_6$
$\mathtt{pre}(au)$							

φ	0	1	0	1	0	0	1
au	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{ extsf{4}}$	$ au_5$	$ au_6$
$\mathtt{pre}(au)$	\perp						

φ	0	1	0	1	0	0	1
au	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_{5}$	$ au_6$
$\mathtt{pre}(au)$	Т	$ au_0$					

				1			
au	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{ extsf{4}}$	$ au_5$	$ au_6$
$ \begin{array}{c c} \operatorname{pre}(\tau) \\ \tau \to \operatorname{pre}(\tau) \end{array} $		$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	τ_5

				1			
au	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{ extsf{4}}$	$ au_5$	$ au_6$
$\mathtt{pre}(au)$	T	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_{5}$
τ -> pre (τ)	$ au_0$						

φ							1
au	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{ extsf{4}}$	$ au_{5}$	$ au_6$
$\mathtt{pre}(au)$	T	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_5$
au -> pre (au)	$ au_0$	$ au_0$					

φ			0				
au	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_5$	$ au_6$
$\mathtt{pre}(au)$	1	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_{5}$
au -> pre (au)	$ au_0$	$ au_{0}$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_{5}$
au when $arphi$							

φ							1
au	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{ extsf{4}}$	$ au_{5}$	$ au_6$
$\mathtt{pre}(au)$	1	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_{5}$
τ -> pre (τ)	$ au_0 $	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_5$
au when $arphi$		$ au_1$					

φ			0				
au	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{ extsf{4}}$	$ au_{5}$	$ au_6$
$\mathtt{pre}(au)$	1	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_{5}$
au -> pre (au)	$ au_0$	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{ extsf{4}}$	$ au_5$
au when $arphi$		$ au_1$		$ au_3$			$ au_6$
$\mid \mathtt{current}(au \ \mathtt{when} \ arphi)$							

CAU

φ			0				
au	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_5$	$ au_6$
$\mathtt{pre}(au)$	1	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_5$
τ -> pre (τ)	$ au_0$	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_5$
au when $arphi$		$ au_1$		$ au_3$			$ au_{6}$
current $(au$ when $arphi)$	_						

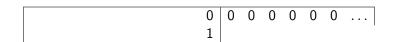
φ			0				
au	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{ extsf{4}}$	$ au_{5}$	$ au_6$
$\mathtt{pre}(au)$	1	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_{5}$
au -> pre (au)	$ au_0$	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_5$
au when $arphi$		$ au_1$		$ au_3$			$ au_6$
current $(au$ when $arphi)$	_	$ au_1$					

φ			0				
au	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{ extsf{4}}$	$ au_{5}$	$ au_6$
$\mathtt{pre}(au)$	1	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_{5}$
au -> pre (au)	$ au_0$	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_5$
au when $arphi$		$ au_1$		$ au_3$			$ au_6$
current $(au$ when $arphi)$	_	$ au_1$	$ au_1$				

φ	0	1	0	1	0	0	1
au	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_5$	$ au_6$
$\mathtt{pre}(au)$	\perp	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{4}$	$ au_{5}$
τ -> pre (τ)	$ au_0$	$ au_0$	$ au_1$	$ au_2$	$ au_3$	$ au_{ extsf{4}}$	$ au_5$
au when $arphi$		$ au_1$		$ au_3$			$ au_6$
$\operatorname{\texttt{current}}(au \ \mathtt{when} \ arphi)$	上	$ au_1$	$ au_1$	$ au_3$	$ au_3$	$ au_3$	$ au_6$

- Note: $[\tau \text{ when } \varphi] = (\tau_1, \tau_3, \tau_6, \ldots)$, *i. e.*, gaps are not filled!
- ▶ This is done by current(τ when φ)

0



```
0 0 0 0 0 0 0 ...

1 1 1 1 1 1 1 ...

n = (0 -> pre(n)+1) 0 1 2 3 4 5 ...

e = (1 -> not pre(e))
```

```
0 0 0 0 0 0 0 ...

1 1 1 1 1 1 ...

n = (0 -> pre(n)+1) 0 1 2 3 4 5 ...

e = (1 -> not pre(e)) 1 0 1 0 1 ...
```

```
0 0 0 0 0 0 0 ...

1 1 1 1 1 1 1 ...

n = (0 -> pre(n)+1) 0 1 2 3 4 5 ...

e = (1 -> not pre(e)) 1 0 1 0 1 0 ...

n when e current(n when e)
```

```
0 0 0 0 0 0 0 0 ...

1 1 1 1 1 1 1 ...

n = (0 -> pre(n)+1) 0 1 2 3 4 5 ...

e = (1 -> not pre(e)) 1 0 1 0 1 0 ...

n when e 0 2 4 ...

current(n when e) 0 0 2 2 4 4 ...

current (n when e) div 2
```

```
0 0 0 0 0 0 0 ...

1 1 1 1 1 1 1 ...

n = (0 -> pre(n)+1) 0 1 2 3 4 5 ...

e = (1 -> not pre(e)) 1 0 1 0 1 0 ...

n when e 0 2 4 ...

current(n when e) 0 0 2 2 4 4 ...

current (n when e) div 2 0 0 1 1 2 2 ...
```

CAU

$$n = 0 \rightarrow pre(n)+1$$

CAU

$n = 0 \rightarrow pre(n)+1$	0	1	2	3	4	5	6	7	8	9	10	11
d2 = (n div 2)*2 = n	1	0	1	0	1	0	1	0	1	0	1	0
n2 = n when $d2$	0		2		4		6		8		10	
d3 = (n div 3)*3 = n	1	0	0	1	0	0	1	0	0	1	0	0
n3 = n when $d3$	0			3			6			9		
d3' = d3 when d2	1		0		0		1		0		0	
n6 = n2 when d3'												

```
n = 0 \rightarrow pre(n)+1
                                                                    10
                                                                         11
     d2 = (n \ div \ 2)*2 = n
                                                                         0
            n2 = n when d2
                                                            8
                                                                    10
     d3 = (n \ div \ 3)*3 = n
                                                                    0
                                                                         0
                                                     6
            n3 = n when d3
          d3' = d3 when d2
                                              0
                                                                    0
                                       0
                                                            0
          n6 = n2 when d3'
c3 = current(n2 when d3')
```

$n = 0 \rightarrow pre(n)+1$	0	1	2	3	4	5	6	7	8	9	10	11
d2 = (n div 2)*2 = n	1	0	1	0	1	0	1	0	1	0	1	0
n2 = n when $d2$	0		2		4		6		8		10	
d3 = (n div 3)*3 = n	1	0	0	1	0	0	1	0	0	1	0	0
n3 = n when $d3$	0			3			6			9		
d3' = d3 when d2	1		0		0		1		0		0	
n6 = n2 when d3'	0						6					
c3 = current(n2 when d3')	0		0		0		6		6		6	

```
node Counter(x0, d:int; r:bool) returns (n:int)
let
  n = x0 → if r then x0 else pre(n) + d
tel
```

```
node Counter(x0, d:int; r:bool) returns (n:int)
let
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tel
```

- lnitial value of n is x0
- If no reset r then increment by d
- ▶ If reset by r, then initialize with x_0
- Counter can be used in other equations, e.g.
 - ightharpoonup ex1 = Counter(0, 2, 0) yields

```
node Counter(x0, d:int; r:bool) returns (n:int)
let
n = x0 → if r then x0 else pre(n) + d
tel
```

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- ► Counter can be used in other equations, e.g.
 - ightharpoonup ex1 = Counter(0, 2, 0) yields the even numbers
 - ightharpoonup ex2 = Counter(0, 1, pre(ex2) = 4) yields

```
node Counter(x0, d:int; r:bool) returns (n:int)
let
  n = x0 → if r then x0 else pre(n) + d
tel
```

- lnitial value of n is x0
- If no reset r then increment by d
- ▶ If reset by r, then initialize with x_0
- ► Counter can be used in other equations, e.g.
 - ightharpoonup ex1 = Counter(0, 2, 0) yields the even numbers
 - ightharpoonup ex2 = Counter(0, 1, pre(ex2) = 4) yields numbers mod 5

ABRO in Lustre

```
node EDGE(X:bool) returns (Y:bool);
let.
 Y = false \rightarrow X \text{ and not pre}(X);
tel
node ABRO (A,B,R:bool) returns (O: bool);
 var seenA. seenB : bool:
let
 0 = EDGE(seenA and seenB);
 seenA = false → not R and (A or pre(seenA));
 seenB = false → not R and (B or pre(seenB));
tel
```

- Synchronous languages have causality problems
- They arise if preconditions of actions are influenced by the actions
- Therefore they require to solve fixpoint equations
- Such equations may have none, one, or more than one solutions
- Analogous to Esterel, one may consider reactive, deterministic, logically correct, and constructive programs

CALU

- $x = \tau$ is acyclic, if x does not occur in τ or does only occur as subterm pre(x) in τ
- **Examples**:
 - a = a and pre(a) is

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- **Examples**:
 - a = a and pre(a) is cyclic

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- **Examples**:
 - a = a and pre(a) is cyclic
 - a = b and pre(a) is

- $x = \tau$ is acyclic, if x does not occur in τ or does only occur as subterm pre(x) in τ
- Examples:
 - a = a and pre(a) is cyclic
 - a = b and pre(a) is acyclic

- $x = \tau$ is acyclic, if x does not occur in τ or does only occur as subterm pre(x) in τ
- **Examples**:
 - a = a and pre(a) is cyclic
 - a = b and pre(a) is acyclic
- Acyclic equations have a unique solution!
- Analyze cyclic equations to determine causality?
- But: Lustre only allows acyclic equation systems
- Sufficient for signal processing

CALU

Malik's Example

▶ However, some interesting examples are cyclic

```
y = if c then y_f else y_g;
y_f = f(x_f);
y_g = g(x_g);
x_f = if c then y_g else x;
x_g = if c then x else y_f;
```

- ▶ Implements if c then f(g(x)) else g(f(x)) with only one instance of f and g
- Impossible without cycles



Sharad Malik.

Analysis of cyclic combinatorial circuits.

in IEEE Transactions on Computer-Aided Design, 1994

Consider the following equations:

```
b = 0 \rightarrow \text{not pre}(b);
y = x + (x when b)
```

► We obtain the following:

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CALU

Consider the following equations:

```
b = 0 \rightarrow \text{not pre}(b);
y = x + (x \text{ when } b)
```

▶ We obtain the following:

```
Х
                           Xη
                                       x_1
                                                    x_2
                                                                X3
                                                                            X_4
                   h
                           0
                                                                             0
       x when b
                                       X1
                                                                X3
x + (x \text{ when } b)
                       x_0 + x_1 \quad x_1 + x_3
                                                x_2 + x_5 \quad x_3 + x_7
                                                                         x_4 + x_9
                                                                                      . . .
```

CAU

Consider the following equations:

```
b = 0 \rightarrow \text{not pre}(b);
y = x + (x \text{ when } b)
```

► We obtain the following:

- ▶ To compute $y_i := x_i + x_{2i+1}$, we have to store x_i, \ldots, x_{2i+1}
- ▶ Problem: not possible with finite memory

- \triangleright Expressions like x + (x when b) are not allowed
- Only streams at the same clock can be combined
- What is the 'same' clock?
- Undecidable to prove this semantically
- Check syntactically

- Two streams have the same clock if their clock can be syntactically unified
- Example:

```
x = a when (y > z);

y = b + c;

u = d when (b + c > z);

v = e when (z < y);
```

Clock Consistency

- Two streams have the same clock if their clock can be syntactically unified
- Example:

$$x = a$$
 when $(y > z)$;
 $y = b + c$;
 $u = d$ when $(b + c > z)$;
 $v = e$ when $(z < y)$;

x and u have the same clock

Clock Consistency

- Two streams have the same clock if their clock can be syntactically unified
- Example:

$$x = a$$
 when $(y > z)$;
 $y = b + c$;
 $u = d$ when $(b + c > z)$;
 $v = e$ when $(z < y)$;

- x and u have the same clock
- x and v do not have the same clock

Arrays

- Given type α , α^n defines an array with n entries of type α
- ► Example: x: boolⁿ
- ► The bounds of an array must be known at compile time, the compiler simply transforms an array of n values into n different variables.
- ▶ The i-th element of an array X is accessed by X[i].
- ▶ X[i..j] with $i \le j$ denotes the array made of elements i to j of X.

Slide 28

Beside being syntactical sugar, arrays allow to combine variables for better hardware implementation.

C A U Synchronous Languages Lecture 18

Example for Arrays

```
node DELAY (const d: int; X: bool) returns (Y: bool);
  var A: bool^(d+1);
let
  A[0] = X;
  A[1..d] = (false^(d)) \rightarrow pre(A[0..d--1]);
  Y = A[d];
tel
```

- ▶ false^(d) denotes the boolean array of length d, which entries are all false
- Observe that pre and -> can take arrays as parameters
- ➤ Since *d* must be known at compile time, this node cannot be compiled in isolation

Example for Arrays

```
node DELAY (const d: int; X: bool) returns (Y: bool);
  var A: bool^(d+1);
let
  A[0] = X;
  A[1..d] = (false^(d)) \rightarrow pre(A[0..d--1]);
  Y = A[d];
tel
```

- ▶ false^(d) denotes the boolean array of length d, which entries are all false
- Observe that pre and -> can take arrays as parameters
- Since d must be known at compile time, this node cannot be compiled in isolation
- ▶ The node outputs each input delayed by *d* steps.
- ▶ So $Y_n = X_{n-d}$ with $Y_n = false$ for n < d

Static Recursion

- Functional languages usually make use of recursively defined functions
- ▶ Problem: termination of recursion in general undecidable
- → Primitive recursive functions guarantee termination
- ► Problem: still with primitive recursive functions, the reaction time depends heavily on the input data
- → Static recursion: recursion only at compile time
- Observe: If the recursion is not bounded, the compilation will not stop.

Example for Static Recursion

Disjunction of boolean array

```
node BigOr(const n:int; x: bool^n) returns (y:bool)
let
y = with n=1 then x[0]
    else x[0] or BigOr(n--1,x[1..n--1]);
tel
```

- Constant n must be known at compile time
- ▶ Node is unrolled before further compilation

Example for Maximum Computation

Static recursion allows logarithmic circuits:

```
node Max(const n:int; x:int^n) returns (y:int)
   var y_1,y_2: int;
let
   y_1 = with n=1 then x[0]
        else Max(n div 2,x[0..(n div 2)--1]);
   y_2 = with n=1 then x[0]
        else Max((n+1) div 2, x[(n div 2)..n--1]);
   y = if y_1 >= y_2 then y_1 else y_2;
tel
```

Delay node with recursion

```
node REC_DELAY (const d: int; X: bool) returns (Y: bool);
let
    Y = with d=0 then X
    else false → pre(REC_DELAY(d--1, X));
tel
```

A call REC_DELAY(3, X) is compiled into something like:

Delay node with recursion

```
node REC_DELAY (const d: int; X: bool) returns (Y: bool);
let
    Y = with d=0 then X
    else false → pre(REC_DELAY(d--1, X));
tel
```

A call REC_DELAY(3, X) is compiled into something like:

```
Y = false → pre(Y2)

Y2 = false → pre(Y1)

Y1 = false → pre(Y0)

Y0 = X;
```

Summary

- Lustre is a synchronous dataflow language.
- ► The core Lustre language are boolean equations and clock operators pre, ->, when, and current.
- Additional datatypes for real and integer numbers are also implemented.
- User types can be defined as in Esterel.
- Lustre only allows acyclic programs.
- Clock consistency is checked syntactically.
- Lustre offers arrays and recursion, but both array-size and number of recursive calls must be known at compile time.

C | A | U Synchronous Languages Lecture 18 Slide 34

To Go Further

- Nicolas Halbwachs and Pascal Raymond, A Tutorial of Lustre, 2002 http://www-verimag.imag.fr/~halbwach/ lustre-tutorial.html
- Nicolas Halbwachs, Paul Caspi, Pascal Raymond, and Daniel Pilaud, The Synchronous Data-Flow Programming Language Lustre, In Proceedings of the IEEE, 79:9, September 1991, http://www-verimag.imag.fr/~halbwach/lustre: ieee.html

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