

# Synchronous Languages—Lecture 12

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*Code Generation for  
Sequential Constructiveness*

# The 5-Minute Review Session

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1. What are *Statecharts*?

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4. What are *SCCharts*? What is their motivation?



## The 5-Minute Review Session

1. What are *Statecharts*? Who invented them?
2. What is the difference between *SyncCharts* and Statecharts?
3. How can we transform Esterel to SyncCharts? How about the other direction?
4. What are *SCCharts*? What is their motivation?
5. What are *Core SCCharts*?

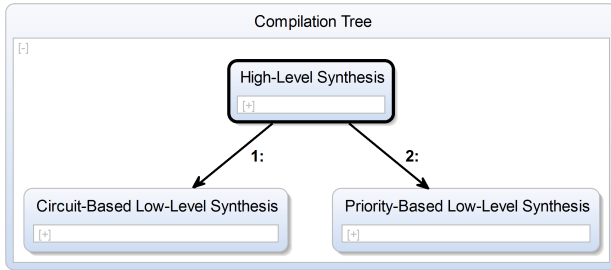
# Overview

SCG Mapping & Dependency Analysis

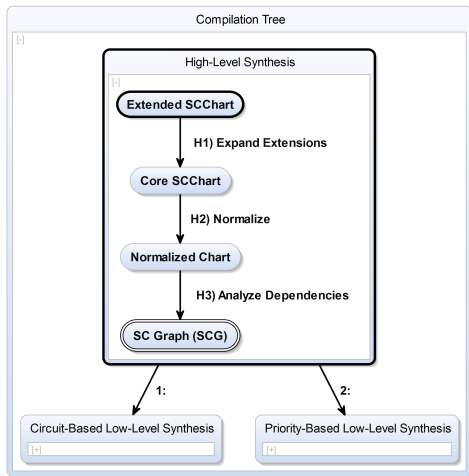
Code Generation Approaches

Schizophrenia Revisited

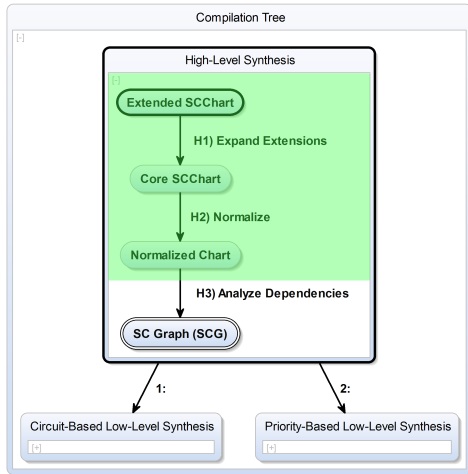
# Compilation — Overview



## Compilation — High-Level Synthesis

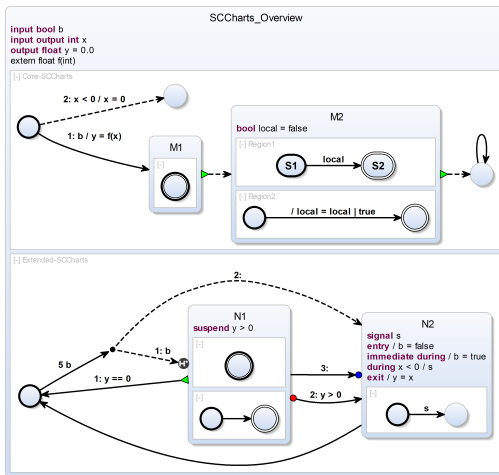


## Compilation — High-Level Synthesis

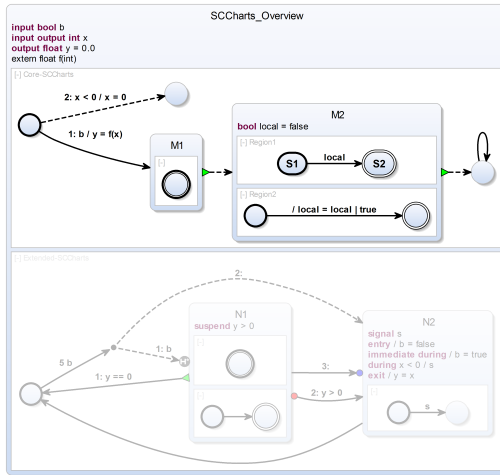


► Green:  
covered in  
previous lecture

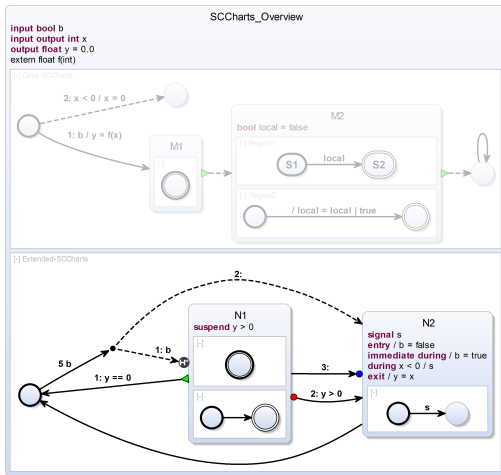
# (Recall) SCCharts - Core & Extended Features



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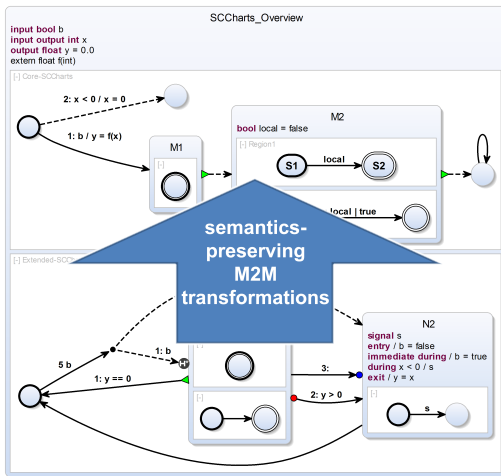


# (Recall) SCCharts - Core & Extended Features

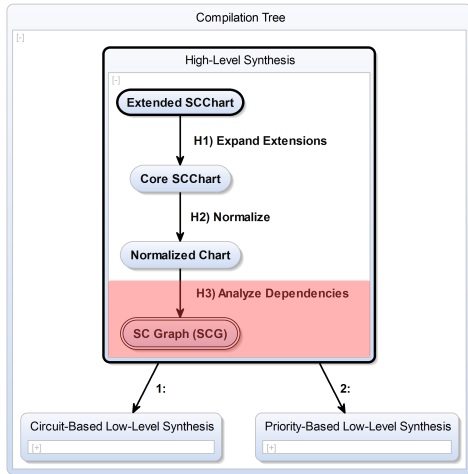




# (Recall) SCCharts - Core & Extended Features



# Compilation — High-Level Synthesis



► Red:  
coming up now

# Overview

## SCG Mapping & Dependency Analysis

- Compilation Overview

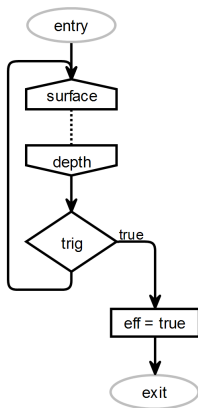
- The SC Graph

- Dependency Analysis

## Code Generation Approaches

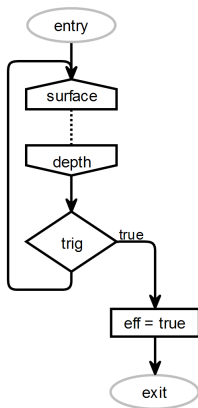
## Schizophrenia Revisited

## The SC Graph



SC Graph:  
Labeled graph  $G = (S, E)$

## The SC Graph

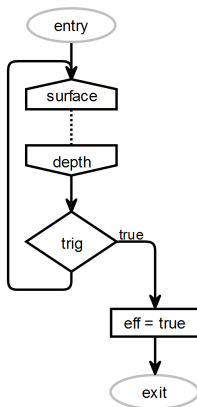


### SC Graph:

Labeled graph  $G = (S, E)$

- ▶ **Nodes**  $S$  correspond to statements of sequential program

## The SC Graph

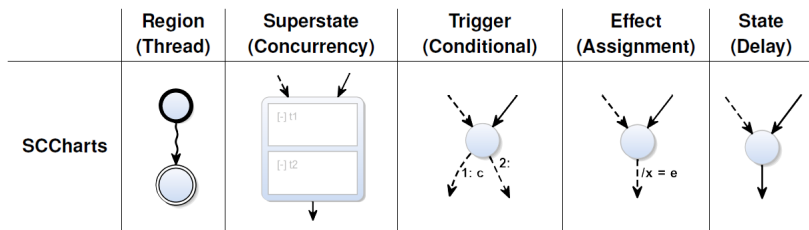


### SC Graph:


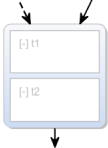
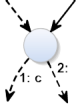
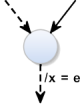
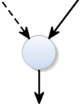

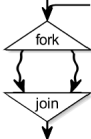
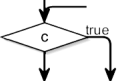

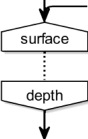
Labeled graph  $G = (S, E)$

- ▶ **Nodes**  $S$  correspond to statements of sequential program
- ▶ **Edges**  $E$  reflect sequential execution control flow

## High-Level Step 3: Map to SC Graph



## High-Level Step 3: Map to SC Graph

	Region (Thread)	Superstate (Concurrency)	Trigger (Conditional)	Effect (Assignment)	State (Delay)
SCCharts					
SCG					
SCL	$t$	fork $t_1$ par $t_2$ join	if ( $c$ ) $s_1$ else $s_2$	$x = e$	pause



# Example: Mapping ABO to SCG

Resource - scccharts/ABO-norm.sct - Eclipse Platform

### ABO

input output bool A  
input output bool B  
output bool O1  
output bool O2

```
graph TD; Init((Init)) -- "/ O1 = false" --> S0((_S0)); S0 -.- "/ O2 = false" -.-> S6((_S6)); S6 -- "/ O2 = true" --> GotAB((GotAB)); subgraph WaitAB; subgraph WaitA; S2((_S2)) -- "1: A" --> S1((_S1)); S1 -- "2:" --> S2; S2 -- "/ B = true" --> S3((_S3)); S3 -- "/ O1 = true" --> DoneA(((DoneA))); end; subgraph WaitB; S4((_S4)) -- "1: B" --> S5((_S5)); S5 -- "2:" --> S4; S4 -- "/ O1 = true" --> S5; S5 -- "/ O1 = true" --> DoneB(((DoneB))); end; DoneA -- "/ O1 = false" --> S6; DoneB -- "/ O1 = false" --> S6; end;
```

### Light-weight Diagram

```
graph TD; Start(( )) --> O1False[O1 = false]; O1False --> O2False[O2 = false]; O2False --> A{A}; A -- true --> BTrue[B = true]; BTrue --> O1True1[O1 = true]; A --> B{B}; B -- true --> O1True2[O1 = true]; O1True1 --> O2True{O2 = true}; O1True2 --> O2True; O2True --> End(( ));
```

#### Diagram Options

Visibility

- Captions
- Hierarchy
- Dependencies
- Non-concurrent dependency
- Confluent dependency
- Basic Blocks
- Scheduling Blocks
- Shadow

Hierarchy: 253.0

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Alignment

- Tick start
- Entry & Exit nodes

Layout

- Dependencies

Orientation:

- Top-Down
- Left-Right

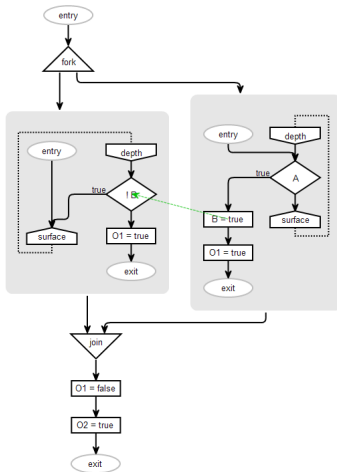
Layout Options

Spacing:

Node Placement:

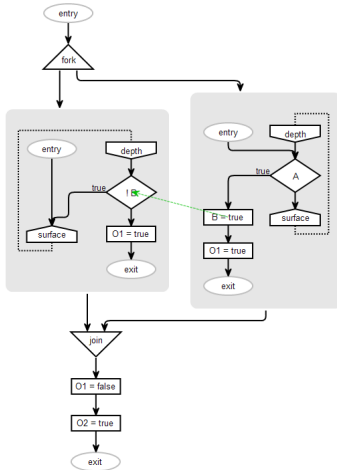
- Simple
- Line

## The SC Graph — Dependencies



Two assignments within the SC Graph are **concurrent** iff

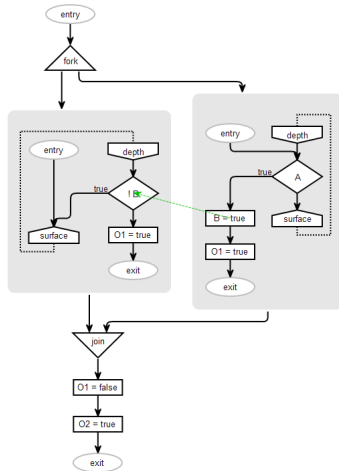
## The SC Graph — Dependencies



Two assignments within the SC Graph are **concurrent** iff

- ▶ they share a *least common ancestor fork* node.

## The SC Graph — Dependencies

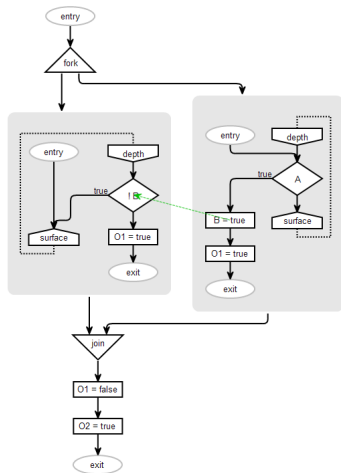


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Two assignments are **confluent** iff

## The SC Graph — Dependencies



Two assignments within the SC Graph are **concurrent** iff

- ▶ they share a *least common ancestor fork* node.

Two assignments are **confluent** iff

- ▶ the order of their assignments does not matter.

## Dependency Types

Dependencies are further categorized in

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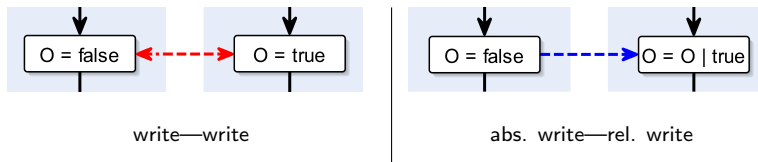
Dependencies are further categorized in



write—write

## Dependency Types

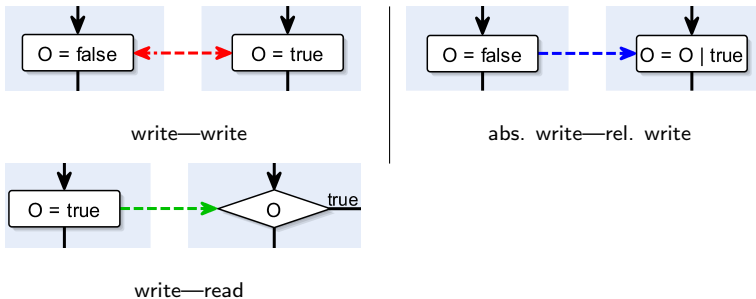
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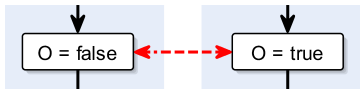
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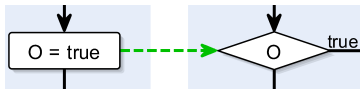


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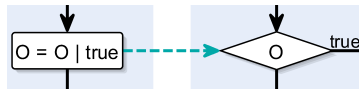
write—write



write—read



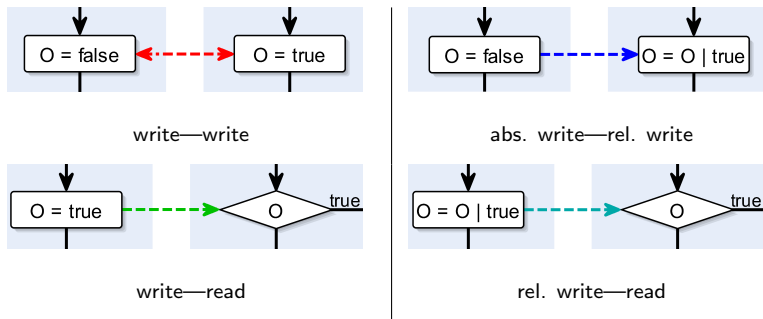
abs. write—rel. write



rel. write—read

## Dependency Types

Dependencies are further categorized in



The SC MoC employs a strict “initialize - update - read” protocol.

(More on the SC MoC will follow in next lecture.)

# Overview

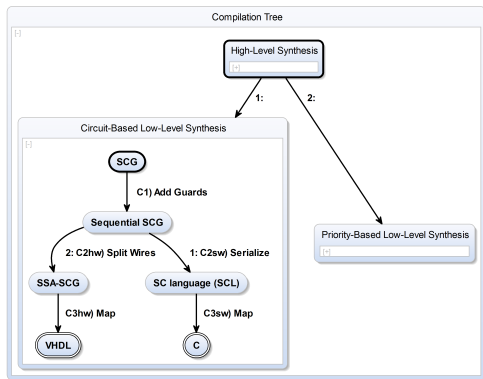
SCG Mapping & Dependency Analysis

Code Generation Approaches

- Circuit-based Approach
- Priority-based Approach
- Approach Comparison

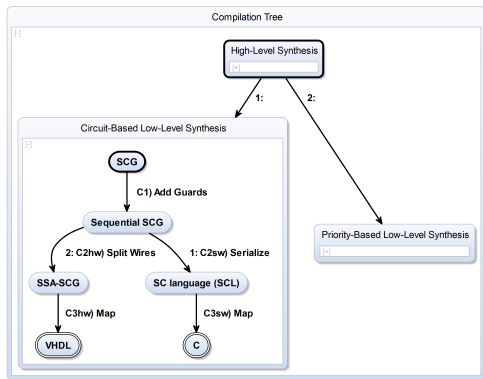
Schizophrenia Revisited

## Low-Level Synthesis I: The Circuit Approach



- ▶ **Basic idea:**  
Generate netlist
- ▶ **Precondition:**  
Acyclic SCG  
(with dependency edges, but without tick edges)
- ▶ Well-established approach for compiling SyncCharts/Esterel

## Low-Level Synthesis I: The Circuit Approach

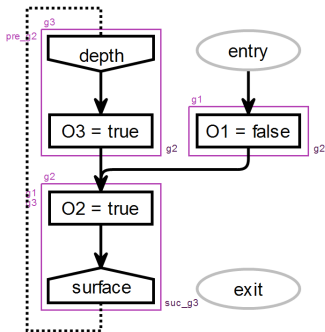


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(with dependency edges, but without tick edges)
- ▶ Well-established approach for compiling SyncCharts/Esterel

### Differences to Esterel circuit semantics [Berry '02]

1. Simpler translation rules, as aborts/traps/suspensions already transformed away during high-level synthesis
2. SC MoC permits sequential assignments

## Basic Blocks

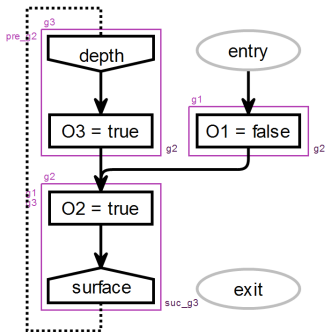


### Basic Block:

A collection of SCG nodes / SCL statements

- ▶ that can be executed monolithically

## Basic Blocks



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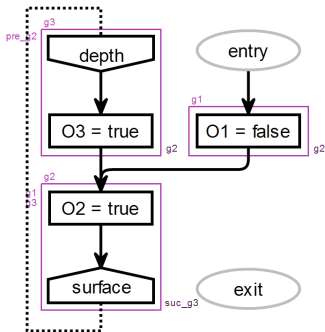
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### Rules:

- ▶ Split at nodes with more than one incoming control flow edge



## Basic Blocks



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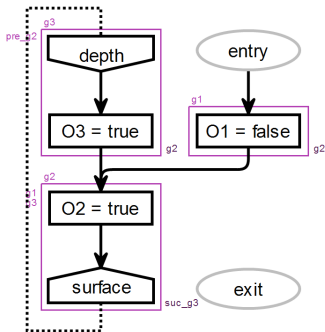
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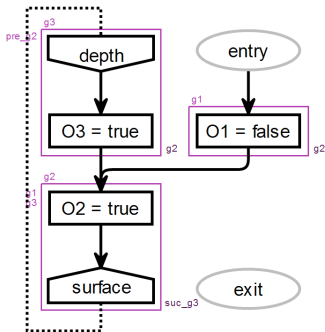
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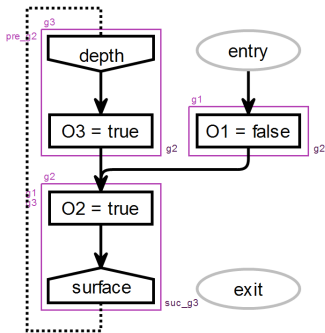
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- ▶ Split after fork nodes and before join nodes

## Basic Blocks



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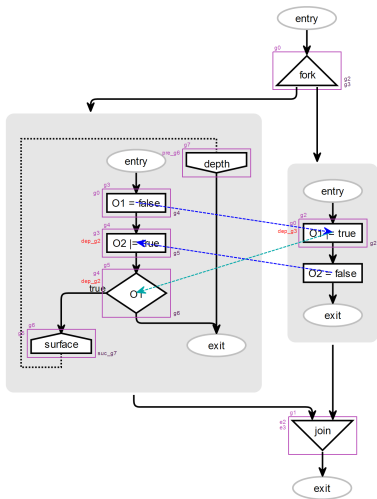
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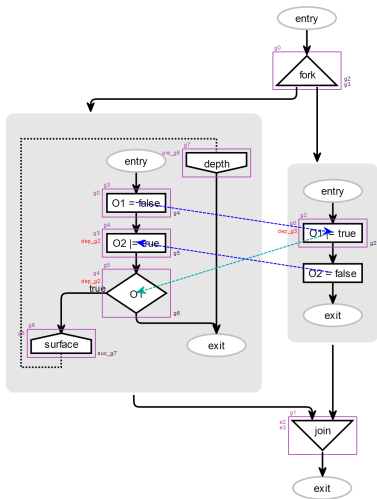
- ▶ Split at nodes with more than one incoming control flow edge
- ▶ Split at nodes with more than one outgoing control flow edge
- ▶ Split at tick edges
- ▶ Split after fork nodes and before join nodes
- ▶ **Each node can only be included in one basic block at any time**

## Scheduling Blocks



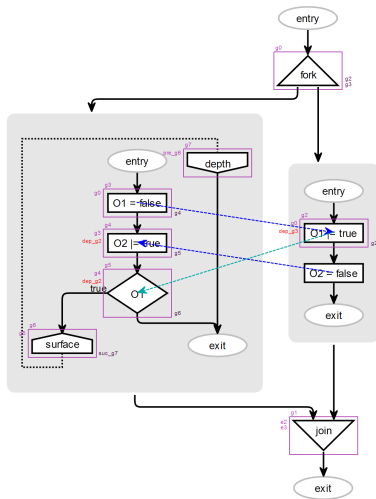
- ▶ Basic blocks may be interrupted when a data dependency interferes.

## Scheduling Blocks



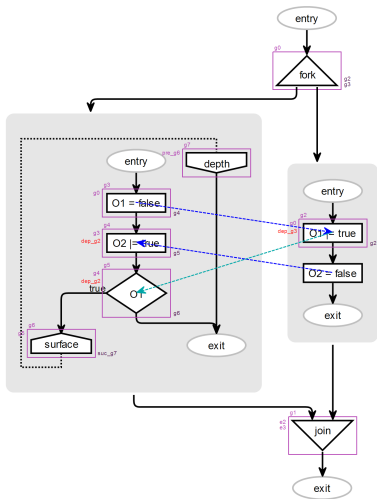
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**Scheduling Blocks**

## Scheduling Blocks



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**Scheduling Blocks**
- ▶ Rules:
  - ▶ Split a basic block at incoming dependency edge

## Scheduling Blocks



- ▶ Basic blocks may be interrupted when a data dependency interferes.
- ▶ Structure basic blocks further:  
**Scheduling Blocks**
- ▶ Rules:
  - ▶ Split a basic block at incoming dependency edge
- ▶ But...
  - ▶ want to minimize the number of context switches
  - ▶ ⇒ Room for optimization!



**Trigger  
(Conditional)**

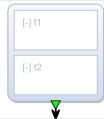
**Effect  
(Assignment)**






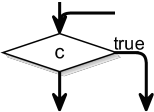
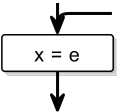
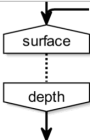
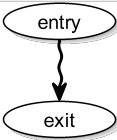
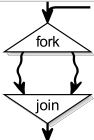
**State  
(Delay)**

**Region  
(Thread)**

**Superstate  
(Concurrency)**

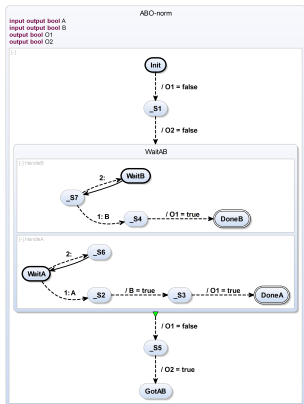
**Normalized  
Core  
SCCharts**



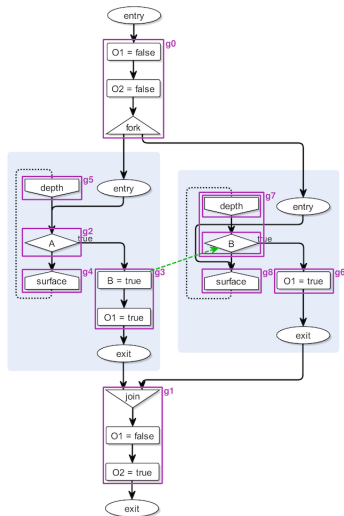
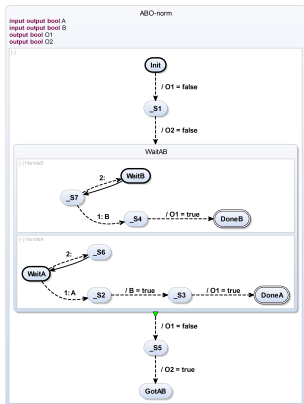
	Trigger (Conditional)	Effect (Assignment)	State (Delay)	Region (Thread)	Superstate (Concurrency)
<b>Normalized Core SCCharts</b>					
<b>SCL</b>	if ( $c$ ) $s_1$ else $s_2$	$x = e$	pause	$t$	fork $t_1$ par $t_2$ join
<b>SCG</b>					

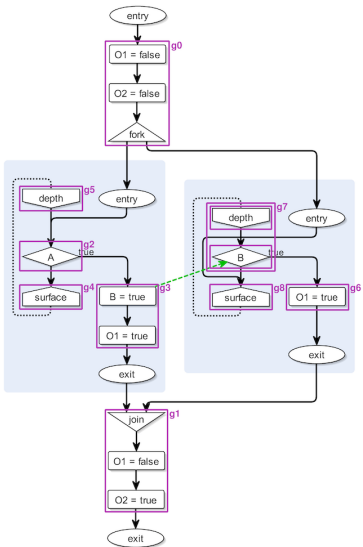
	Trigger (Conditional)	Effect (Assignment)	State (Delay)	Region (Thread)	Superstate (Concurrency)
<b>Normalized Core SCCharts</b>					
<b>SCL</b>	if (c) $s_1$ else $s_2$	$x = e$	pause	$t$	fork $t_1$ par $t_2$ join
<b>SCG</b>					
<b>Data-Flow Code</b>	$g = \vee g_{in}$ $g_{true} = g \wedge c$ $g_{false} = g \wedge \neg c$	$g = \vee g_{in}$ $x' = g ? e : x$	$g_{surf} = \vee g_{in}$ $g_{depth} = \text{pre}(g_{surf})$	$d = g_{exit}$ $m = \neg (g_{fork} \vee \bigvee_{depth \in t} g_{depth})$	$g_{fork} = \vee g_{in}$ $g_{join} = (d_1 \vee m_1) \wedge (d_2 \vee m_2) \wedge (d_1 \vee d_2)$
<b>Circuits</b>					

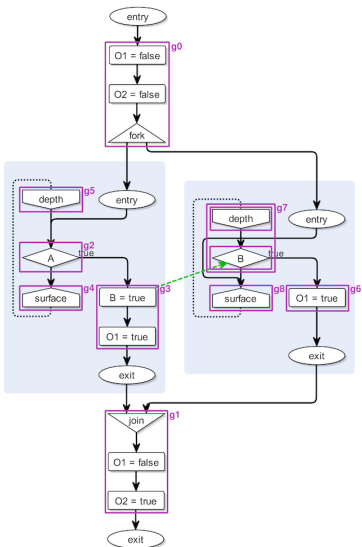
# ABO SCG, With Dependencies and Scheduling Blocks



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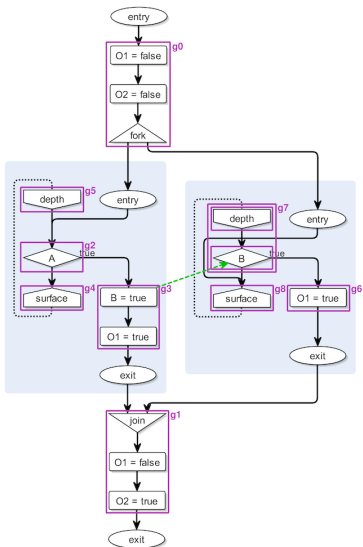




```

1 module ABO
2 input output bool
   A, B;
3 output bool O1,
   O2;
4 {
5   O1 = false;
6   O2 = false;
7   fork
8     HandleA:
9     if (!A) {
10      pause;
11      goto HandleA
12    };
13    B = true;
14    O1 = true;
15  par
16    HandleB:
17    pause;
18    if (!B) {
19      goto HandleB
20    };
21    O1 = true;
22  join;
23  O1 = false;
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25 }

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```

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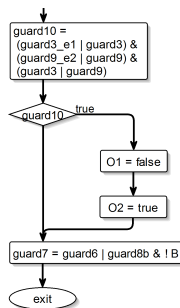
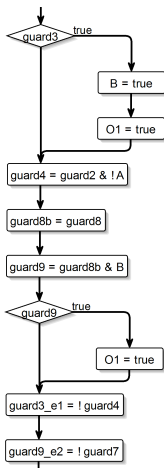
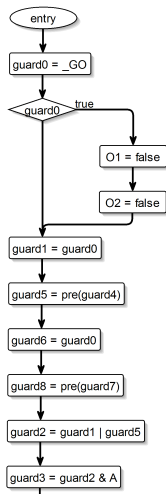
```

2 input output bool A, B;
3 output bool O1, O2;
4 bool GO, g0, g1, ...
5 {
6   g0 = GO;
7   if g0 {
8     O1 = false;
9     O2 = false;
10  };
11  g5 = g4_pre;
12  g7 = g8_pre;
13  g2 = g0 || g5;
14  g3 = g2 && A;
15  if g3 {
16    B = true;
17    O1 = true;
18  };
19  g4 = g2 && !A;
20  g6 = g7 && B;
21  if g6 {
22    O1 = true;
23  };
24  g8 = g0 || (g7 && !B);
25  e2 = !g4;
26  e6 = !g8;
27  g1 = (g3 || e2) &&
28      (g6 || e6) && (g3 ||
29  if g1 {
30    O1 = false;
31    O2 = true;
32  };
33  g4_pre = g4;
34  g8_pre = g8;
35 }

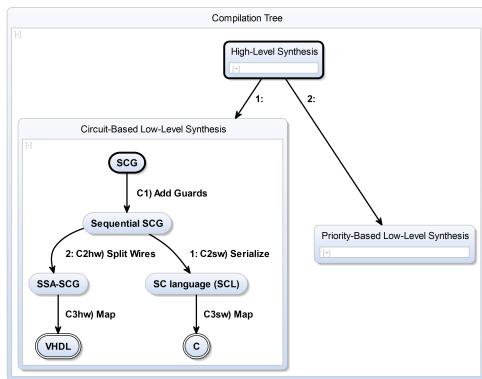
```



## Sequential SCG — ABO



## (Recall) Low-Level Synthesis I: The Circuit Approach



- ▶ Can use sequential SCL directly for SW synthesis
- ▶ Synthesizing HW needs a little further work . . .

## ABO SCL, Logic Synthesis (HW)

```

1 module ABO-seq
2 input output bool A, B;
3 output bool O1, O2;
4 bool GO, g0, g1, ...
5 {
6   g0 = GO;
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```

# ABO SCL, Logic Synthesis (HW)

Difference to software

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2 input output bool A, B;
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4 bool GO, g0, g1, ...
5 {
6   g0 = GO;
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15  if g3 {
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17    O1 = true;
18  };
19  g4 = g2 && ! A;
20  g6 = g7 && B;
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25  e2 = ! g4;
26  e6 = ! g8;
27  g1 = (g3 || e2) && e6;
```



# ABO SCL, Logic Synthesis (HW)

Difference to software

```
1 module ABO-seq
2 input output bool A, B;
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10  };
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12  g7 = g8_pre;
13  g2 = g0 || g5;
14  g3 = g2 && A;
15  if g3 {
16    B = true;
17    O1 = true;
18  };
19  g4 = g2 && ! A;
20  g6 = g7 && B;
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25  e2 = ! g4;
26  e6 = ! g8;
27  g1 = (g3 || e2) &&
```



- ▶ All persistence (state, data) in external reg's ("\_pre"-var's)
- ▶ Permit only one value per wire per tick  $\Rightarrow$  SSA

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Difference to software

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```

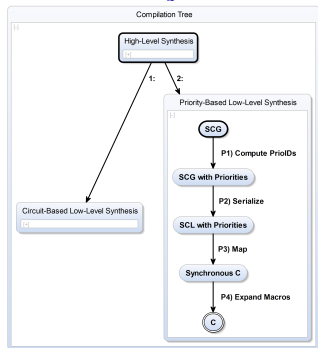


- ▶ All persistence (state, data) in external reg's ("\_pre"-var's)
- ▶ Permit only one value per wire per tick ⇒ SSA

```

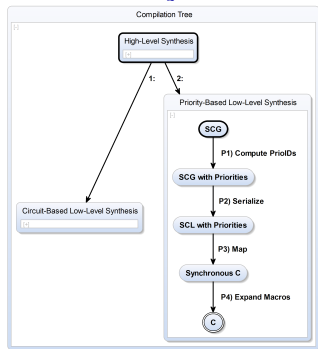
1 ARCHITECTURE behavior OF ABO IS
2 -- local signals definition, hidden
3 begin
4 -- main logic
5 g0 <= GO_local;
6 O1 <= false WHEN g0 ELSE O1_pre;
7 O2 <= false WHEN g0 ELSE O2_pre;
8 g5 <= g4_pre;
9 g7 <= g8_pre;
10 g2 <= g0 or g5;
11 g3 <= g2 and A_local;
12 B <= true WHEN g3 ELSE B_local;
13 O1_2 <= true WHEN g3 ELSE O1;
14 g4 <= g2 and not A_local;
15 g6 <= g7 and B;
16 O1_3 <= true WHEN g6 ELSE O1_2;
17 g8 <= g0 or (g7 and not B);
18 e2 <= not (g4);
19 e6 <= not (g8);
20 g1 <= (g3 or e2) and
    
```

## Low-Level Synthesis II: The Priority Approach



- ▶ More software-like
- ▶ Don't emulate control flow with guards/basic blocks, but with program counters/threads
- ▶ Priority-based thread dispatching
- ▶  $SCL_P$ :  $SCL + PriolDs$
- ▶ Implemented as C macros

## Low-Level Synthesis II: The Priority Approach



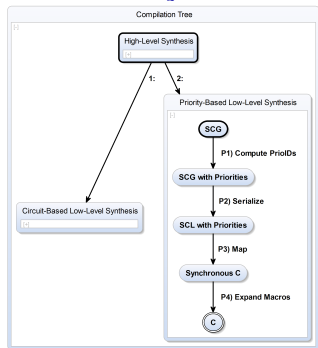
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### Differences to Synchronous C [von Hanxleden '09]

- ▶ No preemption  $\Rightarrow$  don't need to keep track of thread hierarchies
- ▶ Fewer, more light-weight operators
- ▶ RISC instead of CISC



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### Differences to Synchronous C [von Hanxleden '09]

- ▶ No preemption  $\Rightarrow$  don't need to keep track of thread hierarchies
- ▶ Fewer, more light-weight operators
- ▶ RISC instead of CISC
- ▶ More human-friendly syntax

# SCL<sub>P</sub> Macros I

```
1 // Declare Boolean type
2 typedef int bool;
3 #define false 0
4 #define true 1
5
6 // Generate "_L<line-number>" label
7 #define _concat_helper(a, b) a ## b
8 #define _concat(a, b) _concat_helper(a, b)
9 #define _label_ _concat(_L, __LINE__)
10
11 // Enable/disable threads with prioID p
12 #define _u2b(u) (1 << u)
13 #define _enable(p) _enabled |= _u2b(p); _active |= _u2b(p)
14 #define _isEnabled(p) ((_enabled & _u2b(p)) != 0)
15 #define _disable(p) _enabled &= ~_u2b(p)
```

## SCL<sub>P</sub> Macros II

```
17 // Set current thread continuation
18 #define _setPC(p, label) _pc[p] = &&label
19
20 // Pause, resume at <label> or at pause
21 #define _pause(label) _setPC(_cid, label); goto _L_PAUSE
22 #define pause      _pause(_label_); _label_:
23
24 // Fork/join sibling thread with prioID p
25 #define fork1(label, p) _setPC(p, label); _enable(p);
26 #define join1(p)      _label_: if (_isEnabled(p)) { _pause(_label_); }
27
28 // Terminate thread at "par"
29 #define par          goto _L_TERM;
30
31 // Context switch (change prioID)
32 #define _prio(p)     _deactivate(_cid); _disable(_cid); _cid = p; \
33 _enable(_cid); _setPC(_cid, _label_); goto _L_DISPATCH; _label_:
```

# ABO SCL<sub>P</sub> I

```
85 int tick()
86 {
87     tickstart(2);
88     O1 = false;
89     O2 = false;
90
91     fork1(HandleB,
92           1) {
93         HandleA:
94         if (!A) {
95             pause;
96             goto HandleA
97             ;
98         }
99         B = true;
100        O1 = true;
101    } par {
```



```
85 int tick()
86 {
87     if (!_notInitial) { _active = _enabled;
88         goto _L_DISPATCH; } else { _pc[0]
89         = &&_L_TICKEND; _enabled = (1 <<
90         0); _active = _enabled; _cid = 2;
91         ; _enabled |= (1 << _cid); _active
92         |= (1 << _cid); _notInitial = 1;
93         } ;
94     O1 = 0;
95     O2 = 0;
96
97     _pc[1] = &&HandleB; _enabled |= (1 <<
98     1); _active |= (1 << 1); {
99     HandleA:
100    if (!A) {
101        _pc[_cid] = &&_L94; goto _L_PAUSE;
102        _L94:;
103        goto HandleA;
104    }
105    B = 1;
106    O1 = 1;
107
108    } goto _L_TERM; {
```

## ABO SCL<sub>P</sub> II

```
102 HandleB:
103 pause;
104 if (!B) {
105     goto HandleB
106     ;
107 }
108 O1 = true;
109 } join1(2);
110 O1 = false;
111 O2 = true;
112 tickreturn;
113 }
```



```
102 HandleB:
103     _pc[_cid] = &&_L103; goto _L_PAUSE;
104     _L103;;
105     if (!B) {
106         goto HandleB;
107     }
108     O1 = 1;
109 } _L108: if (((_enabled & (1 << 2)) !=
110     0)) { _pc[_cid] = &&_L108; goto
111     _L_PAUSE; };
112 O1 = 0;
113 O2 = 1;
114 goto _L_TERM; _L_TICKEND: return (
115     _enabled != (1 << 0)); _L_TERM:
116     _enabled &= ~(1 << _cid); _L_PAUSE
117     : _active &= ~(1 << _cid);
118     _L_DISPATCH: __asm volatile("bsrl
119     %1,%0\n" : "=r" (_cid) : "r" (
120     _active) ); goto *_pc[_cid];
121 }
122 }
```

## Comparison of Low-Level Synthesis Approaches

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	Circuit	Priority
--	---------	----------

## Comparison of Low-Level Synthesis Approaches

	<b>Circuit</b>	<b>Priority</b>
Accepts instantaneous loops	-	+
Can synthesize hardware	+	-
Can synthesize software	+	+

## Comparison of Low-Level Synthesis Approaches

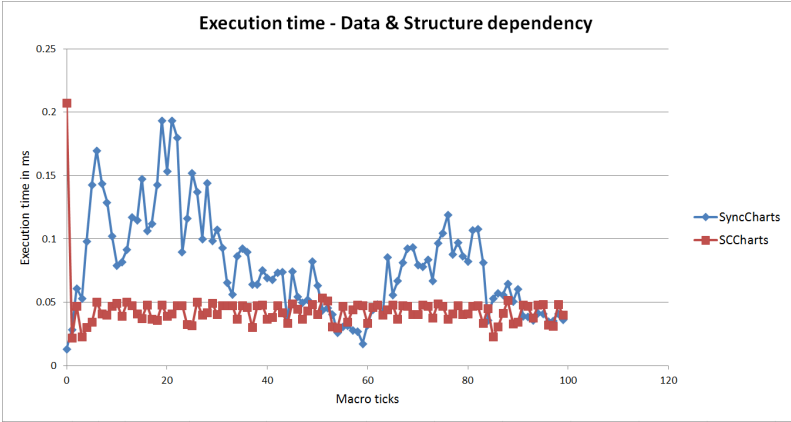
	<b>Circuit</b>	<b>Priority</b>
Accepts instantaneous loops	-	+
Can synthesize hardware	+	-
Can synthesize software	+	+
Size scales well (linear in size of SCChart)	+	+



## Comparison of Low-Level Synthesis Approaches

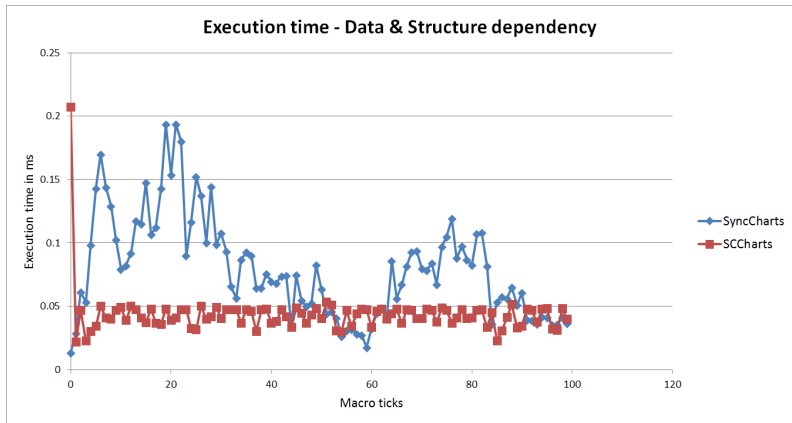
	Circuit	Priority
Accepts instantaneous loops	-	+
Can synthesize hardware	+	-
Can synthesize software	+	+
Size scales well (linear in size of SCChart)	+	+
Speed scales well (execute only "active" parts)	-	+
Instruction-cache friendly (good locality)	+	-
Pipeline friendly (little/no branching)	+	-
WCRT predictable (simple control flow)	+	+/-
Low execution time jitter (simple/fixed flow)	+	-

# Comparison — Jitter



Execution time comparison of statecharts with multiple hierarchies depicts

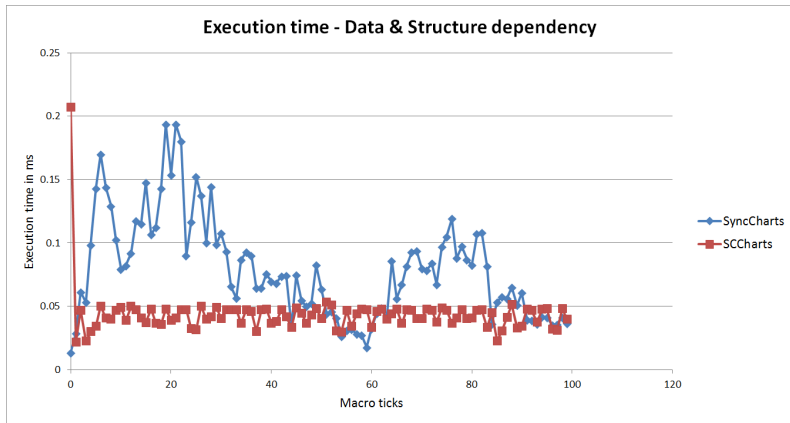
# Comparison — Jitter



Execution time comparison of statecharts with multiple hierarchies depicts

- ▶ low jitter in circuit-based approach

# Comparison — Jitter



Execution time comparison of statecharts with multiple hierarchies depicts

- ▶ low **jitter** in circuit-based approach
- ▶ execution time in priority-based approach more dependant to structure and input data of the statechart

# Overview

SCG Mapping & Dependency Analysis

Code Generation Approaches

Schizophrenia Revisited

- Classic Approaches

- The SCL Solution

- Summary

## ... What About That Acyclicity?

```
1 module schizo
2   output O;
3
4   loop
5     signal S in
6       present S
7       then
8         emit O
9       end;
10    pause;
11    emit S;
12  end;
13 end loop
14 end module
```

Esterel

[Tardieu & de Simone '04]

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```



```

1 module schizo-conc
2 output bool O;
3 {
4   while (true) {
5     bool S, _Term;
6
7     fork
8       _Term = false;
9       O = S;
10      pause;
11      S = S || true;
12      _Term = true;
13    par
14      while (true) {
15        S = false;
16        if (_Term)
17          break;
18        pause;
19      }
20    join;
21  }
22 }
    
```

SCL (1st try)

Esterel  
 [Tardieu & de Si-  
 mone '04]

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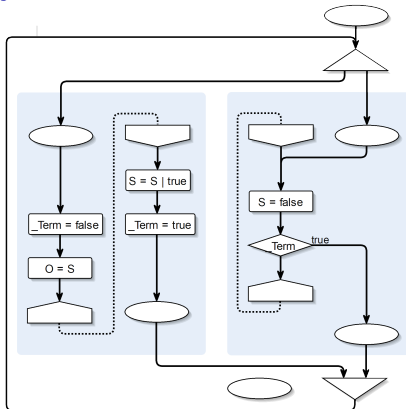
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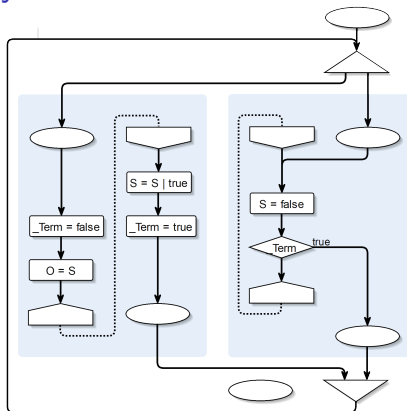
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Q: The problem?

SCL (1st try)

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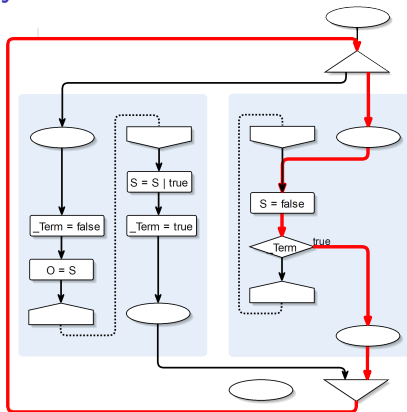
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Esterel  
 [Tardieu & de Si-  
 mone '04]

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```



Q: The problem?

A: Instantaneous loop!

SCL (1st try)

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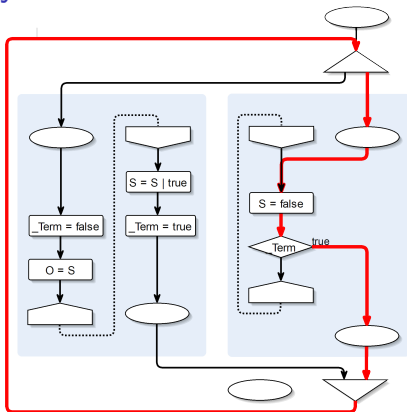


Esterel  
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17          break;
18        pause;
19      }
20    join;
21  }
22 }
    
```

SCL (1st try)



Q: The problem?

A: Instantaneous loop!  
 a.k.a. Signal reincarnation  
 a.k.a. Schizophrenia

## A Solution

```
1 module schizo
2   output O;
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4   loop
5     signal S in
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Esterel

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```



```

1 module schizo-cured
2 output O;
3
4 loop
5   signal S in
6     present S then
7       emit O
8     end;
9     pause;
10    emit S;
11  end;
12  signal S' in
13    present S' then
14      emit O
15    end;
16    pause;
17    emit S';
18  end;
19 end loop
    
```

- ▶ Duplicated loop body to separate signal instances
- ▶ Q: Complexity?

Esterel

## A Solution

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1 module schizo
2 output O;
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Esterel



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13    present S' then
14      emit O
15    end;
16    pause;
17    emit S';
18  end;
19 end loop
    
```

- ▶ Duplicated loop body to separate signal instances
- ▶ Q: Complexity?
- ▶ A: Exponential 😞

## A Better Solution

```
1 module schizo
2 output O;
3
4 loop
5   signal S in
6     present S
7     then
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9     end;
10    pause;
11    emit S;
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```

Esterel

## A Better Solution

```

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6     present S
7     then
8       emit O
9     end;
10    pause;
11    emit S;
12  end;
13 end loop
14 end module
    
```



```

1 module
2 schizo-cured2-str1
3 output O;
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- ▶ Duplicated loop body
- ▶ “Surface copy” transfers control immediately to “depth copy”

Esterel

[Tardieu & de Simone  
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 (simplified)



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- ▶ **Caveat:** We only talk about **signal** reincarnation, *i. e.*, instantaneously exiting and entering a signal scope
- ▶ Reincarnated **statements** still require duplication (quadratic worst case?)

## SCG for schizo-cured

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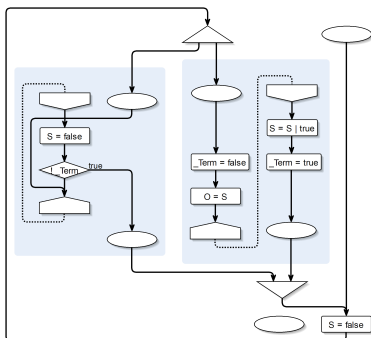
SCL



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- ▶ Cycle now broken by delay
- ▶ Only the “depth initialization” of S creates a concurrent “initialize before update” scheduling dependence

SCL

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- ▶ Recall the equations for joining (two) threads:

$g_{join} = (d_1 \vee m_1) \wedge (d_2 \vee m_2) \wedge (d_1 \vee d_2)$ , where for each thread  $t_i$  it is “done”  $d_i = g_{exit}$  and “empty”  $m_i = \neg(g_{fork} \vee \bigvee_{depth \in t_i} g_{depth})$

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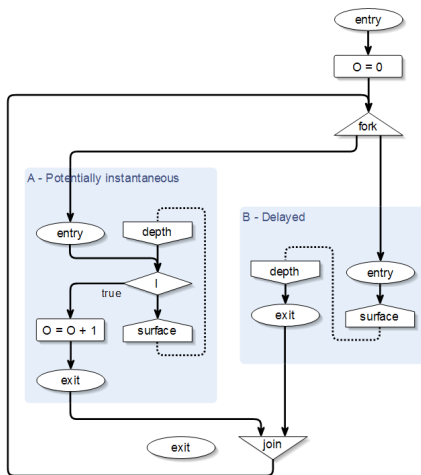
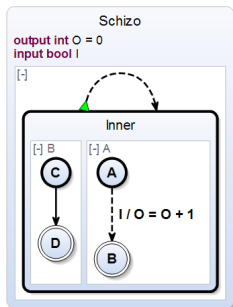
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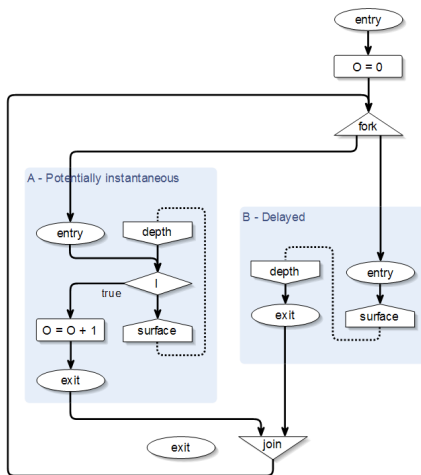
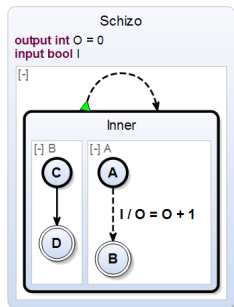
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- ▶ In SCG, if thread terminates instantaneously in non-instantaneous parallel, we end in **unjoined exit**, visualized with small solid disk

# Statement Reincarnation



- Consider  $I$  absent in initial tick, present in next tick

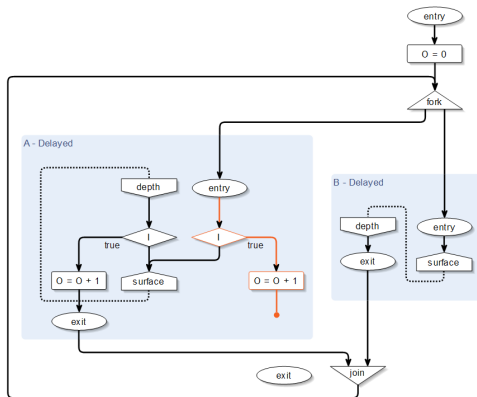
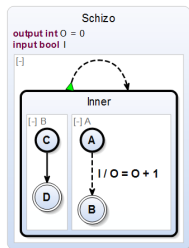
# Statement Reincarnation



- ▶ Consider  $I$  absent in initial tick, present in next tick
- ▶ Must then increment  $O$  twice



# Statement Reincarnation



- ▶ To remove cycle, must duplicate the part of the surface of the thread that might instantaneously terminate, i.e., nodes on instantaneous path from entry to exit
- ▶ The second increment of O leads to unjoined exit

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4. Treating advanced constructs as syntactic sugar simplifies down-stream synthesis (CISC vs. RISC)
5. **Plenty of future work:** compilation of Esterel-like languages, trade-off RISC vs. CISC, WCRT analysis, timing-predictable design flows (→ PRETSY), multi-clock, visualization, ...

## To Go Further

- ▶ J. Aguado, M. Mendler, R. von Hanxleden, I. Fuhrmann. *Grounding Synchronous Deterministic Concurrency in Sequential Programming*. In Proceedings of the 23rd European Symposium on Programming (ESOP'14), Grenoble, France, April 2014.  
<https://rtsys.informatik.uni-kiel.de/~biblio/downloads/papers/esop14.pdf>
- ▶ R. von Hanxleden, M. Mendler, J. Aguado, B. Duderstadt, I. Fuhrmann, C. Motika, S. Mercer, O. O'Brien, and P. Roop. *Sequentially Constructive Concurrency – A Conservative Extension of the Synchronous Model of Computation*. ACM Transactions on Embedded Computing Systems, Special Issue on Applications of Concurrency to System Design, July 2014, 13(4s).  
<https://rtsys.informatik.uni-kiel.de/~biblio/downloads/papers/tecs14.pdf>