

Synchronous Languages—Lecture 13

Prof. Dr. Reinhard von Hanxleden

Christian-Albrechts Universität Kiel
Department of Computer Science
Real-Time Systems and Embedded Systems Group

15 Dec. 2016

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*Sequentially Constructive
Concurrency*

The 5-Minute Review Session

1. How do *SCCharts* and *SyncCharts* differ?

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3. What is the *SCG*?
4. What are *basic blocks*? What are *scheduling blocks*?
5. When compiling from the *SCG*, what types of *low-level synthesis* do we distinguish? How do they compare?

Safety-Critical Embedded Systems



- ▶ Embedded systems often safety-critical

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- ▶ Safety-critical systems must react deterministically

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- ▶ Safety-critical systems must react deterministically
- ▶ Computations often exploit *concurrency*
- ▶ **Key challenge:**
Concurrency must be deterministic!

Thanks to Michael Mendler (U Bamberg) for support with these slides

Implementing (Deterministic) Concurrency

- ▶ **C, Java, etc.:**

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Aim: Deterministic concurrency with synchronous foundations, but without synchronous restrictions.

Comparing Both Worlds

Sequential Languages

- ▶ C, Java, ...

Synchronous Languages

- ▶ Esterel, Lustre, Signal, SCADE, SyncCharts ...

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Sequential Languages

- ▶ C, Java, ...
- ▶ Asynchronous schedule

Synchronous Languages

- ▶ Esterel, Lustre, Signal, SCADE, SyncCharts ...
- ▶ Clocked, cyclic schedule

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 - ☺ Deterministic concurrency and deadlock freedom

Comparing Both Worlds (Cont'd)

Sequential Languages

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 - ☺ Deterministic concurrency and deadlock freedom
 - ☹ Heavy restrictions by constructiveness analysis

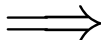
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Sequentially Constructive Model of Computation (SC MoC)

- 😊 Deterministic concurrency and deadlock freedom
- 😊 Intuitive programming paradigm

Implementing **Deterministic** Concurrency: SC MoC

- ▶ **Concurrent** micro-step control flow

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- ▶ **Sequential** micro-step control flow

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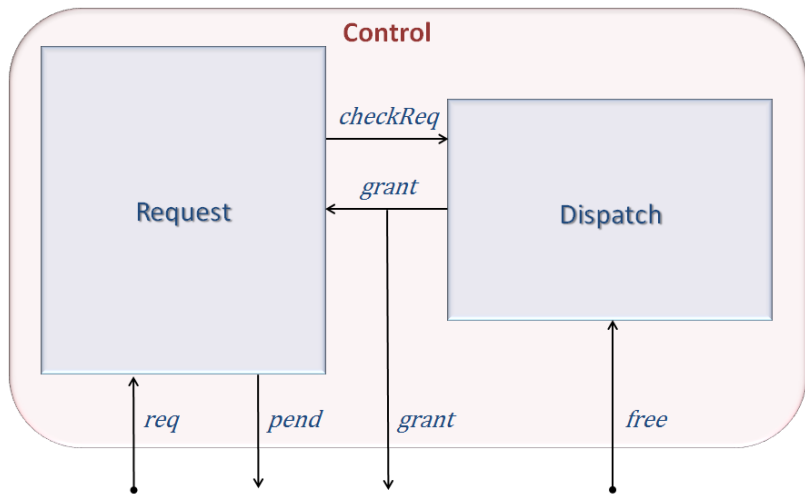
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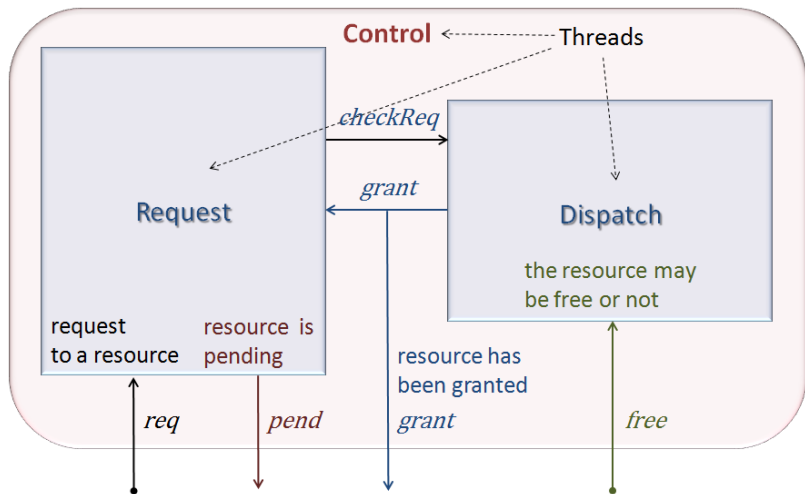
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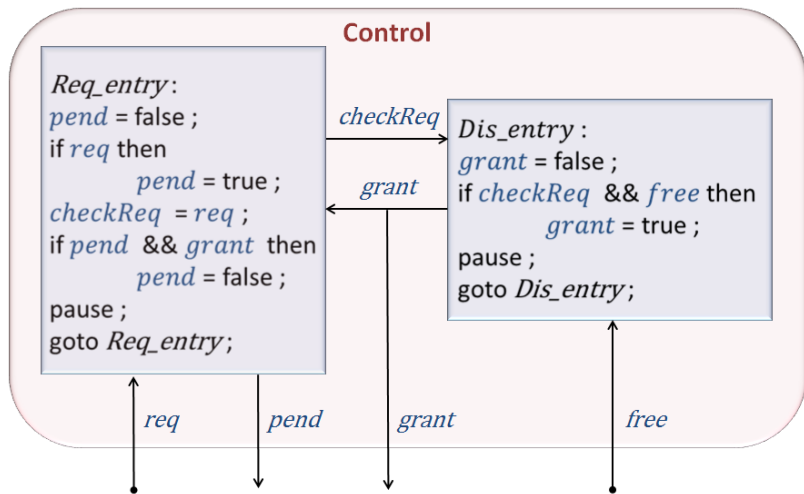
A Sequentially Constructive Program



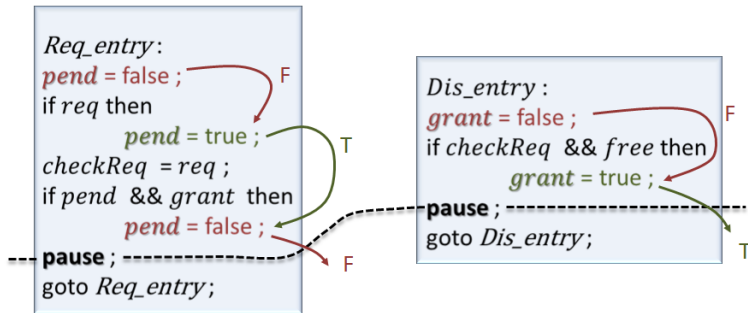
A Sequentially Constructive Program (Cont'd)



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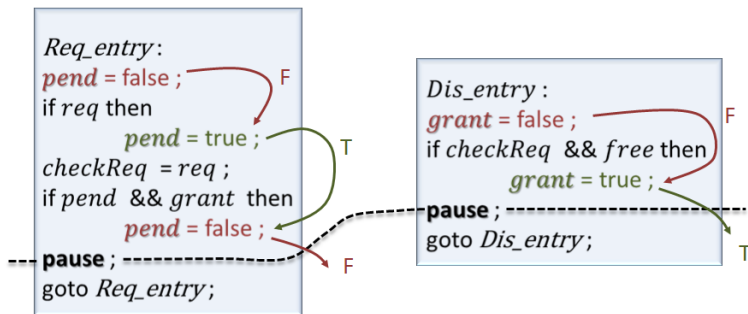


A Sequentially Constructive Program (Cont'd)



Imperative program order (sequential access to shared variables)

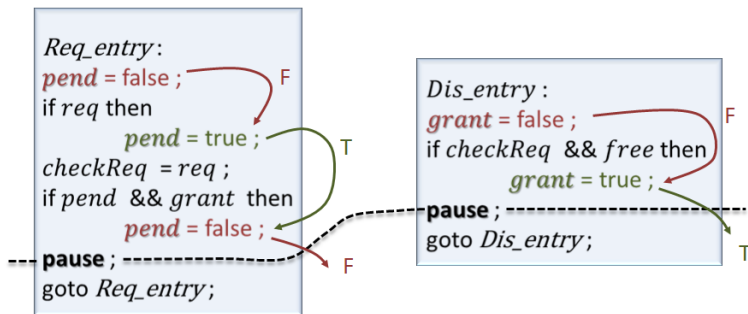
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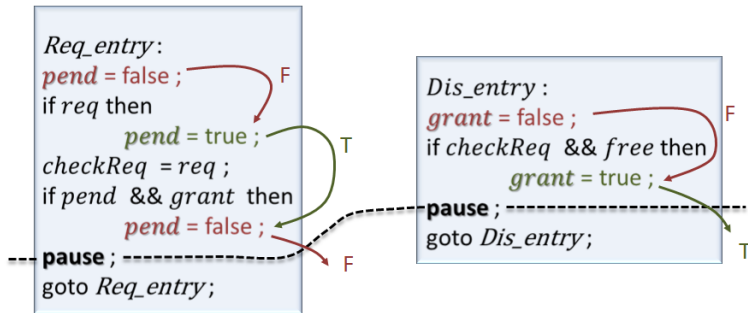
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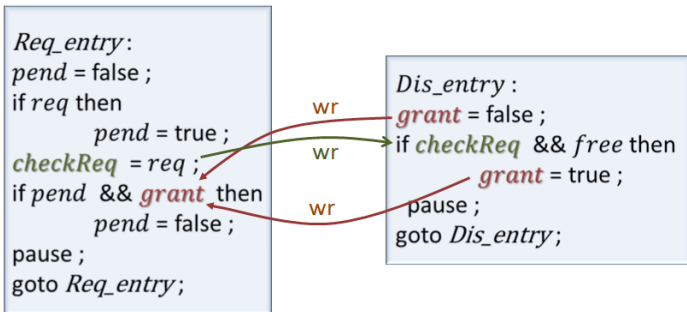
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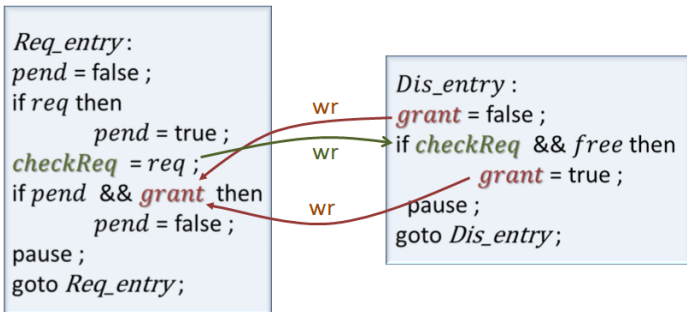
- ▶ “write-after-write” can change value sequentially
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 - ☺ Accepted in SC MoC
 - ☹ Not permitted in standard synchronous MoC

A Sequentially Constructive Program (Cont'd)



Concurrency scheduling constraints (access to shared variables):

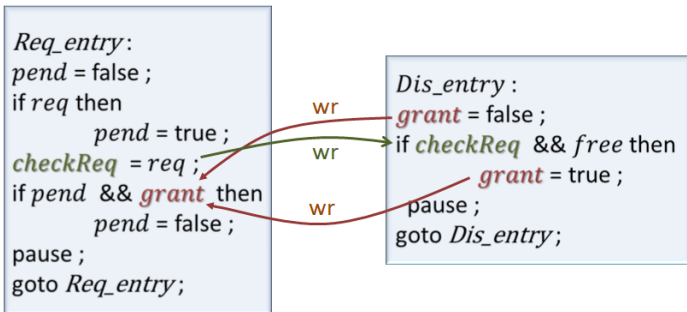
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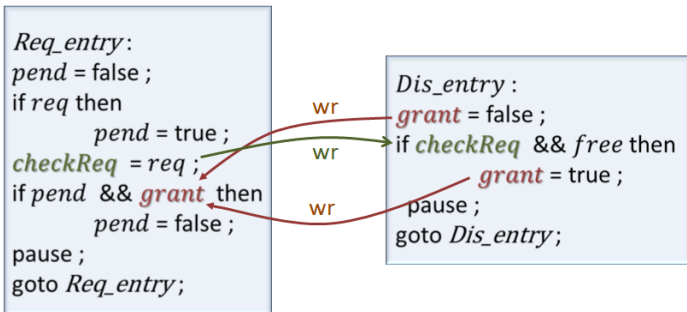
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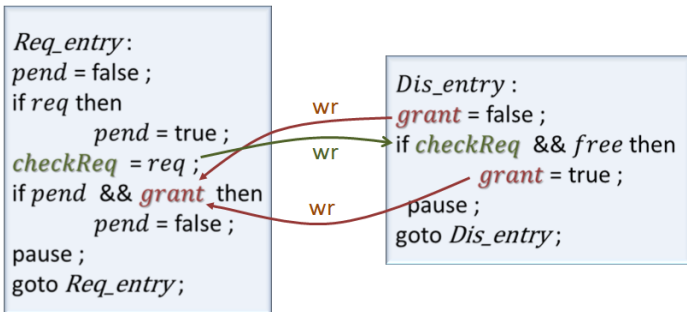
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- ▶ Implemented by the SC compiler

A Constructive Game of Schedulability

logically reactive program



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- ▶ Defines the rules
- ▶ Prescribes sequential execution order
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- ▶ “Free Schedules”

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- ▶ Determines winning strategy
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- ▶ Tries to choose a *spoiling execution* from admissible schedules

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deadlocks, oscillation,
non-determinism,
metastability



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The following applies to **concurrent** variable accesses only ...

Organizing Concurrent Variable Accesses

SC Concurrent Memory Access Protocol (per macro tick)



concurrent, multi-writer, multi-reader variables

Organizing Concurrent Variable Accesses

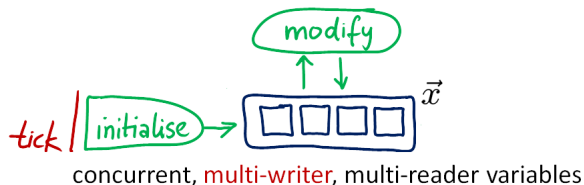
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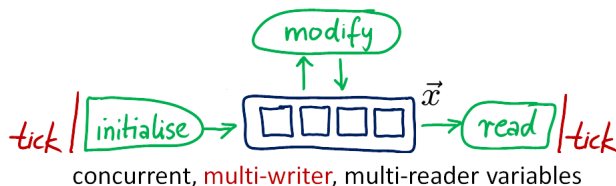
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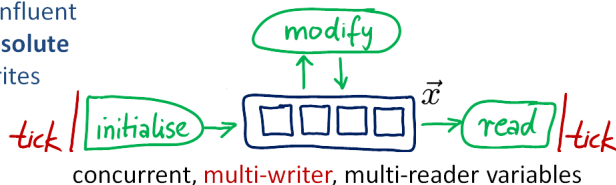
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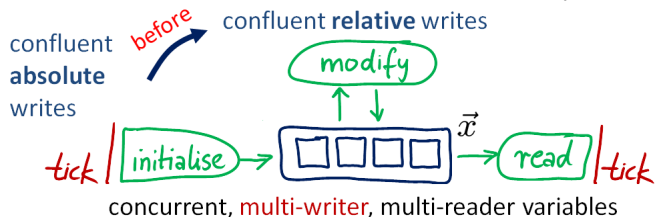
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confluent
absolute
writes



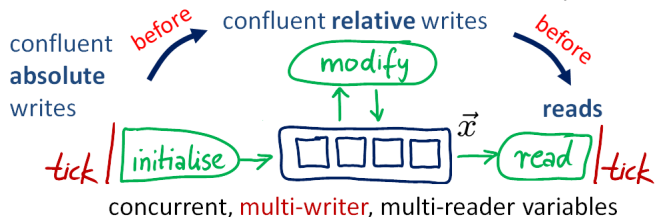
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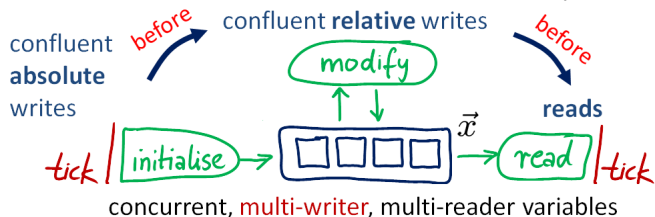
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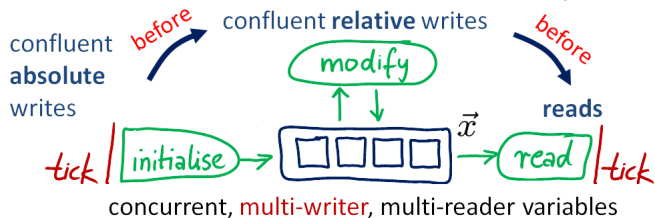
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Confluent Statements (per macro tick)

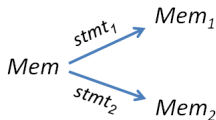
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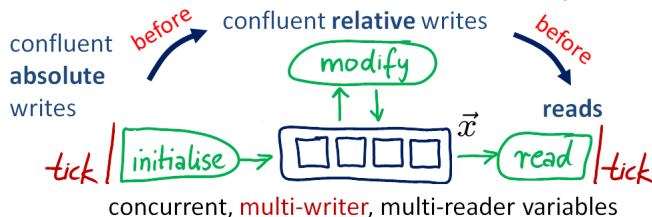
For all memories
 Mem, reachable
 in macro tick:



stmt₁, stmt₂
 concurrent

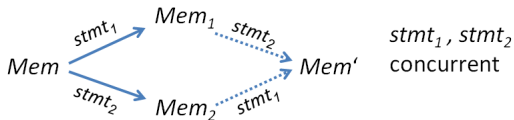
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Goals and Challenges

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Goals and Challenges

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2. Want maximal freedom without compromising determinacy
 - ▶ A determinate program should also be SC
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3. Want to exploit sequentiality as much as possible
 - ▶ But what exactly *is* sequentiality?

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 - ▶ An SC program must be determinate
3. Want to exploit sequentiality as much as possible
 - ▶ But what exactly *is* sequentiality?
4. Want to define not only the exact concept of SC, but also a practical strategy to implement it
 - ▶ In practice, this requires conservative approximations
 - ▶ Compiler must not accept Non-SC programs
 - ▶ Compiler may reject SC programs

References

Most of the material here draws from this reference [TECS]:



R. von Hanxleden, M. Mendler, J. Aguado, B. Duderstadt, I. Fuhrmann, C. Motika, S. Mercer, O. O'Brien, and P. Roop.

Sequentially Constructive Concurrency – A Conservative Extension of the Synchronous Model of Computation.

ACM Transactions on Embedded Computing Systems, Special Issue on Applications of Concurrency to System Design, July 2014, 13(4s).

<http://rtsys.informatik.uni-kiel.de/~biblio/downloads/papers/tecs14.pdf>

Unless otherwise noted, the numberings of definitions, sections etc. refer to this.

There is also an extended version [TR]:



R. von Hanxleden, M. Mendler, J. Aguado, B. Duderstadt, I. Fuhrmann, C. Motika, S. Mercer, O. O'Brien, and P. Roop.

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<http://rtsys.informatik.uni-kiel.de/~biblio/downloads/papers/report-1308.pdf>

Overview

Motivation

Formalizing Sequential Constructiveness (SC)

The SC Language (SCL) and the SC Graph (SCG) [Sec. 2]

Free Scheduling of SCGs [Sec. 3]

The SC Model of Computation [Sec. 4]

Wrap-Up

The Sequentially Constructive Language (SCL) [Sec. 2.1]

- ▶ Foundation for the SC MoC

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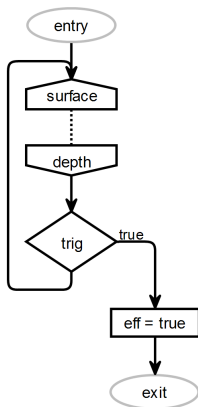
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$$s ::= x = e \mid s; s \mid \mathbf{if} (e) s \mathbf{else} s \mid / : s \mid \mathbf{goto} / \mid \\ \mathbf{fork} s \mathbf{par} s \mathbf{join} \mid \mathbf{pause}$$

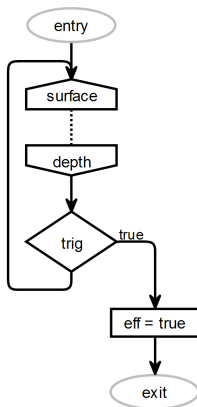
- s Statement
- x Variable
- e Expression
- $/$ Program label

The SC Graph (SCG) [Sec. 2.3]



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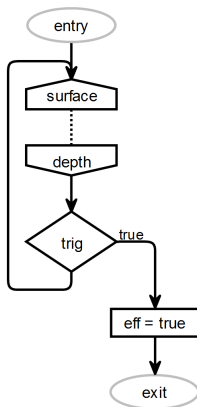


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Internal representation for

- ▶ Semantic foundation
- ▶ Analysis
- ▶ Code generation

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SC Graph:

Labeled graph $G = (N, E)$

- ▶ **Nodes** N correspond to statements of sequential program
- ▶ **Edges** E reflect sequential execution control flow

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- ▶ $n.st \in$
{entry, exit, goto, $x = ex$, if(ex), fork, join, surf, depth}
- ▶ x : variable, ex : expression.

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- ▶ **flow edges** $\alpha_{flow} =_{\text{def}} \{seq, tick\}$

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Edge $e \in E$ has edge type $e.type \in \alpha_a$

- ▶ Specifies the nature of the particular ordering constraint expressed by e
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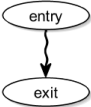
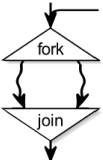
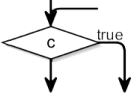

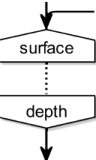
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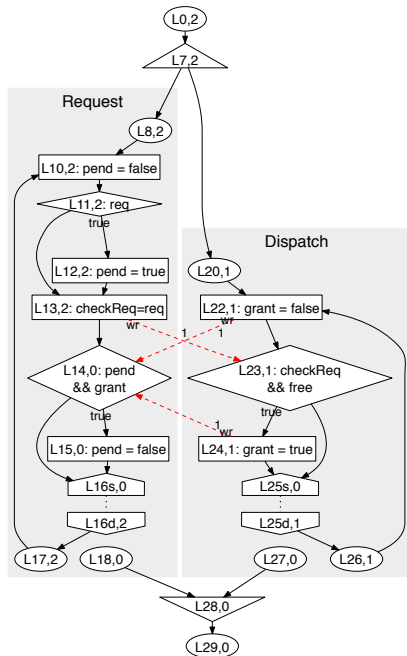
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Mapping SCL & SCG

	Thread (Region)	Concurrency (Superstate)	Conditional (Trigger)	Assignment (Effect)	Delay (State)
SCG					
SCL	t	fork t_1 par t_2 join	if (c) s_1 else s_2	$x = e$	pause

Plus “;” (Sequence) and “goto” to specify sequential successors (solid edges)

SCL & SCG – The Control Example



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Static Threads [Sec. 2.4]

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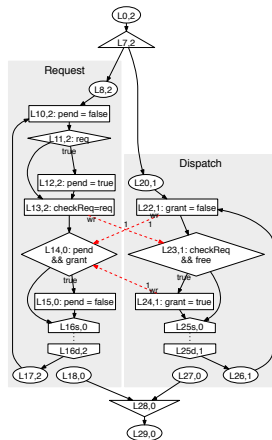
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- ▶ For each thread t , define $sts(t)$ as the **set of statement nodes** $n \in N$ such that $th(n) = t$

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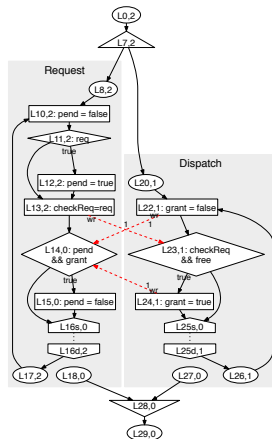
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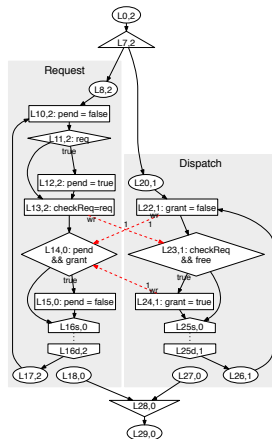


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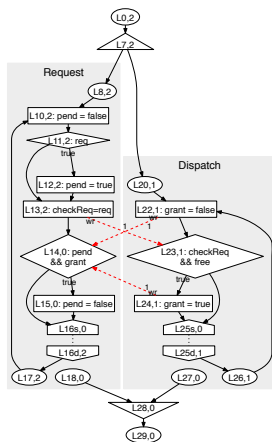
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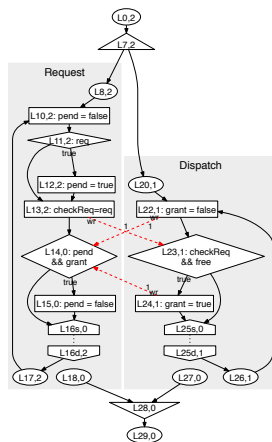
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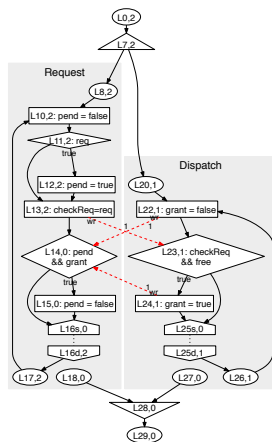
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- ▶ The remaining statement nodes of N are partitioned into
 $sts(Dispatch)$ and $sts(Request)$

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- ▶ t_1 is **subordinate** to t_2 , written $t_1 \prec t_2$, if $t_1 \neq t_2 \wedge t_1 \in p^*(t_2)$

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- ▶ $p^*(t) =_{def} \{t, p(t), p(p(t)), \dots, \text{Root}\}$, the recursively defined set of **ancestor threads** of t
- ▶ t_1 is **subordinate** to t_2 , written $t_1 \prec t_2$, if $t_1 \neq t_2 \wedge t_1 \in p^*(t_2)$
- ▶ t_1 and t_2 are (**statically**) **concurrent**, denoted $t_1 \parallel t_2$, iff t_1 and t_2 are descendants of distinct threads sharing a common fork node, *i. e.*:

Static Thread Concurrency and Subordination [Def. 2.2]

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 - ▶ Denote this common fork node as $lcafork(t_1, t_2)$, the **least common ancestor fork**
 - ▶ Lift (static) concurrency notion to nodes: $n_1 \parallel n_2 \Leftrightarrow th(n_1) \parallel th(n_2) \Leftrightarrow lcafork(n_1, n_2) = lcafork(th(n_1), th(n_2))$

Concurrency and Subordination in Control-Program

```

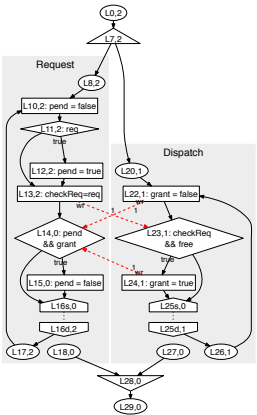
1  module Control
2  input bool free, req;
3  output bool grant, pend;
4  {
5    bool checkReq;
6
7    fork {
8      // Thread Request
9      Request entry:
10     pend = false;
11     if (req)
12       pend = true;
13     checkReq = req;
14     if (pend && grant)
15       pend = false;
16     pause;
17     goto Request entry;
18   }

```

```

19  par {
20    // Thread Dispatch
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26     goto Dispatch entry;
27   }
28  join;
29 }

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Concurrency and Subordination in Control-Program

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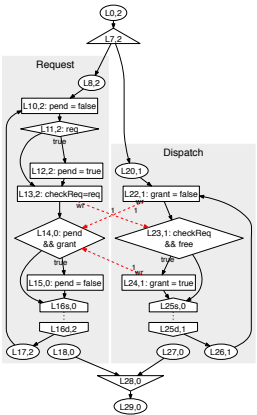
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► Root \prec Request and Root \prec Dispatch

Concurrency and Subordination in Control-Program

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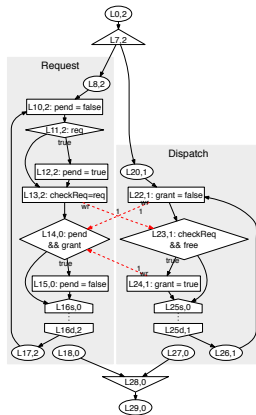
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- ▶ $Root \prec Request$ and $Root \prec Dispatch$
- ▶ $Request \parallel Dispatch$

Concurrency and Subordination in Control-Program

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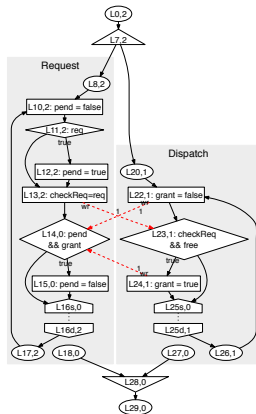
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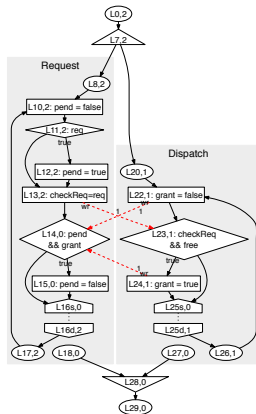


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Concurrency and Subordination in Control-Program

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- ▶ $Root \prec Request$ and $Root \prec Dispatch$
- ▶ $Request \parallel Dispatch$, $Root$ is not concurrent with any thread

Note: Concurrency on threads, in contrast to concurrency on node instances, is purely static and can be checked with a simple, syntactic analysis of the program structure.

Thread Trees [TR, Sec. 3.7]

- A **Thread Tree** illustrates the static thread relationships.
- ▶ Contains subset of SCG nodes:
 1. Entry nodes, labeled with names of their threads
 2. Fork nodes, attached to the entry nodes of their threads
 - ▶ Similar to the AND/OR tree of Statecharts

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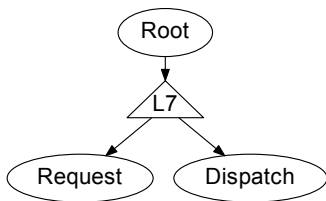
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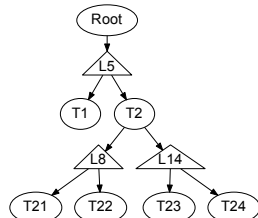
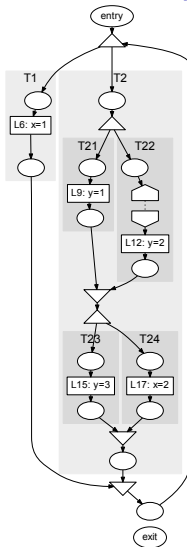


Thread Trees – The Reinc2 Example

```

1  module Reinc2
2  output int x, y;
3  {
4  loop:
5  fork { // Thread T1
6  x = 1; }
7  par { // Thread T2
8  fork { // Thread T21
9  y = 1; }
10 par { // Thread T22
11 pause;
12 y = 2; }
13 join;
14 fork { // Thread T23
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Alternative definition for static thread concurrency:

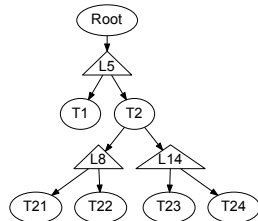
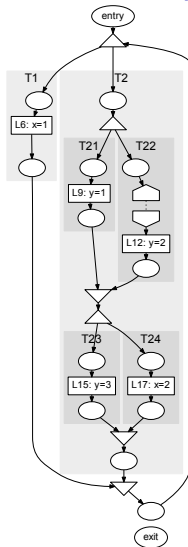
- Threads are concurrent iff

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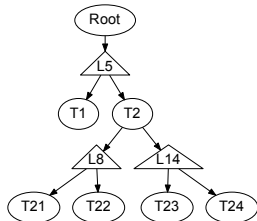
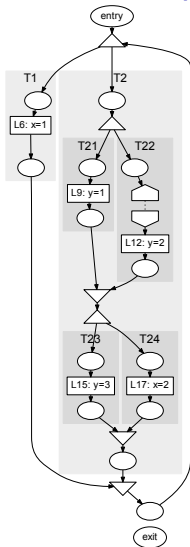
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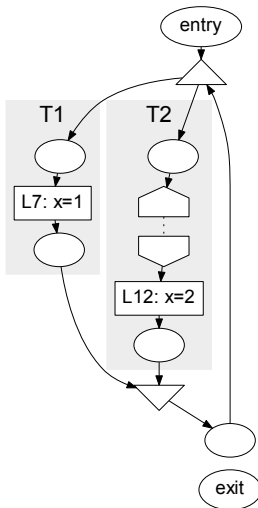
- Threads are concurrent iff their least common ancestor (lca) in thread tree is a fork node

Thread Reincarnation – The Reinc Example

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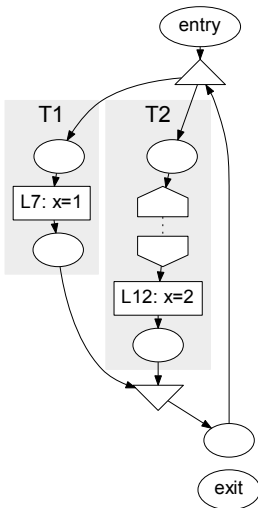


Are interested in **run-time concurrency**, *i. e.*, whether ordering is up to discretion of a scheduler.

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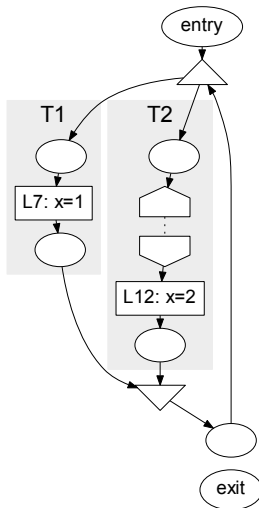
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Observations:

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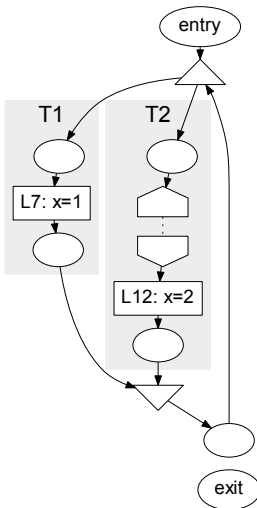
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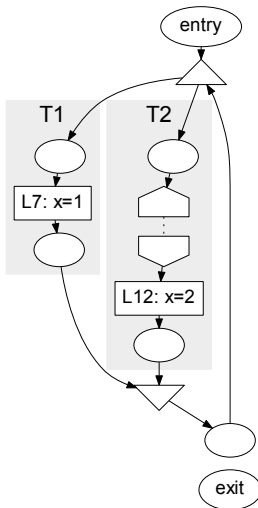
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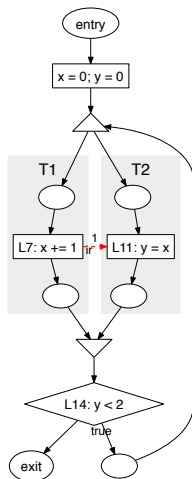


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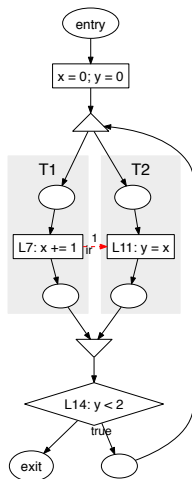
- ▶ T2 exhibits **thread reincarnation**
- ▶ Assignments to x are both executed in the same tick, yet are sequentialized
- ▶ Thus, **static thread concurrency not sufficient to capture run-time concurrency!**

Statement Reincarnation I



```
1  module InstLoop
2  output int x = 0, y = 0;
3  {
4  loop:
5  fork {
6    // Thread T1
7    x += 1;
8  }
9  par {
10   // Thread T2
11   y = x;
12 }
13 join;
14 if (y < 2)
15   goto loop;
16 }
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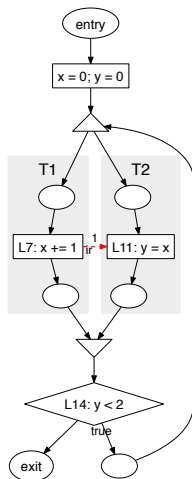
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- ▶ Accesses to x in $L7$ and $L11$ executed twice within tick
- ▶ Denote this as **statement reincarnation**

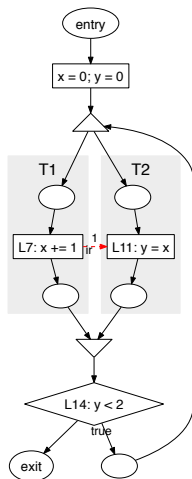
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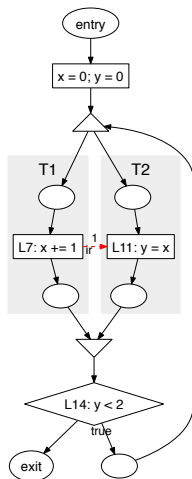
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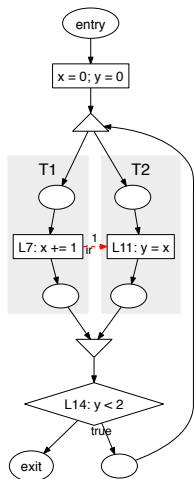
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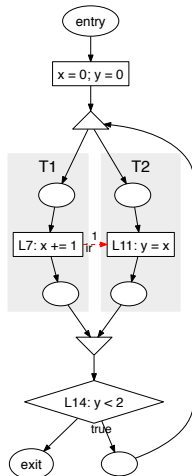


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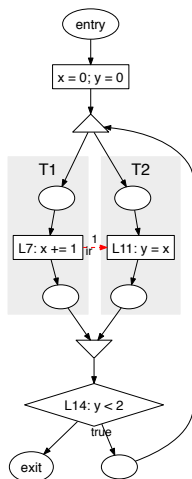
Not enough to impose an order on the program statements
 \Rightarrow Need to distinguish **statement instances**

Statement Reincarnation II



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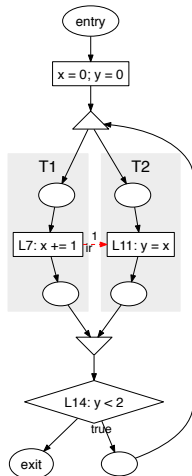
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Reject

Statement Reincarnation II

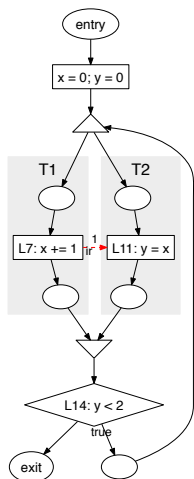


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☹ Traditional synchronous languages: Reject

▶ *Instantaneous loops* traditionally forbidden

Statement Reincarnation II



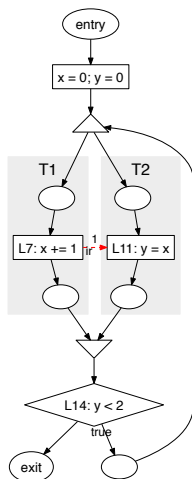
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2  output int x = 0, y = 0;
3  {
4  loop:
5  fork {
6    // Thread T1
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9  par {
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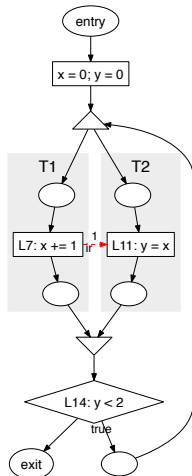
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▶ One might still want to ensure that a program **always terminates**

▶ But this issue is **orthogonal to determinacy** and having a well-defined semantics.

Macroticks [Def. 2.3 + 2.4]

- ▶ Given: SCG $G = (N, E)$
- ▶ (Macro) tick R , of length $len(R) \in \mathbb{N}_{\geq 1}$:
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 $\{(n, i) \mid 1 \leq i \leq len(R), n = R(i)\}$

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Given: macro tick R , index $1 \leq i \leq \text{len}(R)$, node $n \in N$

Def.: $\text{last}(n, i) = \max\{j \mid j \leq i, R(j) = n\}$,

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3. their threads have been instantiated by the same instance of the associated least common ancestor fork, i. e., $\text{last}(n, i_1) = \text{last}(n, i_2)$ where $n = \text{lcafork}(n_1, n_2)$

Overview

Motivation

Formalizing Sequential Constructiveness (SC)

The SC Language (SCL) and the SC Graph (SCG) [Sec. 2]

Free Scheduling of SCGs [Sec. 3]

The SC Model of Computation [Sec. 4]

Wrap-Up

Continuations & Thread Execution States [Def. 3.1]

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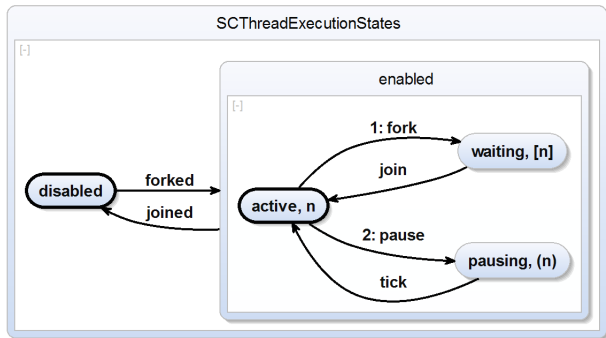
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In a trace (see later slide), round/square/no parentheses around $n = c.node$ denote $c.status$, for enabled continuations c

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A configuration is called **valid** if C is valid

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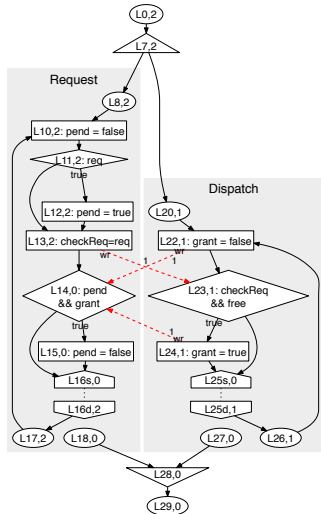
1  module Control
2  input bool free, req;
3  output bool grant, pend;
4  {
5    bool checkReq;
6
7    fork {
8      // Thread Request
9      Request entry:
10     pend = false;
11     if (req)
12       pend = true;
13     checkReq = req;
14     if (pend && grant)
15       pend = false;
16     pause;
17     goto Request entry;
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```

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19  par {
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21    Dispatch entry:
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25     pause;
26     goto Dispatch entry;
27  }
28  join;
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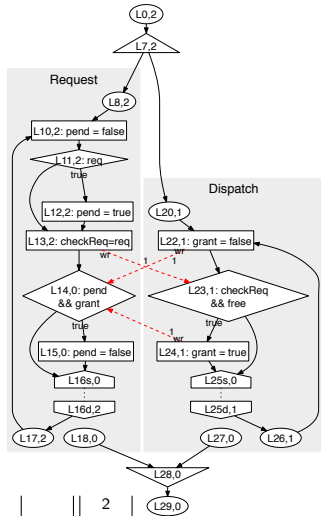
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Macro tick	<i>a</i>		2															2
Micro tick	<i>i</i>		1	2	3	4	5	6	7	8	9	10	11	12	13			13
Input vars	free	<i>t</i>																<i>t</i>
vars	req	<i>t</i>																<i>t</i>
Output vars	grant	<i>f</i>								<i>f</i>		<i>t</i>						<i>t</i>
vars	pend	<i>f</i>		<i>f</i>		<i>t</i>								<i>f</i>				<i>f</i>
Local var	checkReq	<i>f</i>					<i>t</i>											<i>t</i>
	C_{Root}		[L28]															[L28]
Continuations	$C_{Request}$		L16d	L10	L11	L12	L13	L14	L14	L14	L14	L14	L14	L15	L16s			(L16s)
	$C_{Dispatch}$		L25d	L25d	L25d	L25d	L25d	L25d	L22	L23	L24	L25s	(L25s)	(L25s)	(L25s)			(L25s)
Scheduled nodes	R_i^a		L16d	L10	L11	L12	L13	L25d	L22	L23	L24	L25s	L14	L15	L16s			

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2. Do so in an interleaving fashion

Micro Steps I

Micro step: transition $(C_{cur}, M_{cur}) \xrightarrow{c}_{\mu s} (C_{nxt}, M_{nxt})$ between two micro ticks

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- ▶ c : continuation selected for execution
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The **free schedule** is permitted to pick any one of the \prec -maximal continuations $c \in C_{cur}$ with $c.status = active$ and execute it in the current memory M_{cur}

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(Recall:) Micro step: transition $(C_{cur}, M_{cur}) \xrightarrow{c}_{\mu s} (C_{nxt}, M_{nxt})$

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- ▶ Actions μM and μC (made precise in paper) depend on the statement $c.node.st$ to be executed
- ▶ (C_{nxt}, M_{nxt}) uniquely determined by c , thus may write $(C_{nxt}, M_{nxt}) = c(C_{cur}, M_{cur})$

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Quiescent configuration (C, M) :

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Global clock step $V_I : (C_{cur}, M_{cur}) \rightarrow_{tick} (C_{nxt}, M_{nxt})$

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- ▶ All pausing continuations of C advance from their surf node to the associated depth node:

$$C_{nxt} = \{c[\text{active} :: tick(n)] \mid c[\text{pausing} :: n] \in C_{cur}\} \cup \{c[\text{waiting} :: n] \mid c[\text{waiting} :: n] \in C_{cur}\}$$

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Formally,

$$M_{nxt}(x) = \begin{cases} v_i, & \text{if } x = x_i \in I, \\ M_{cur}(x), & \text{if } x \notin I. \end{cases}$$

Macro Ticks

Scheduler runs through sequence

$$(C_0^a, M_0^a) \xrightarrow{c_1^a}_{\mu s} (C_1^a, M_1^a) \xrightarrow{c_2^a}_{\mu s} \cdots \xrightarrow{c_{k(a)}^a}_{\mu s} (C_{k(a)}^a, M_{k(a)}^a) \quad (1)$$

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Sequence (1) is **macro tick** (**synchronous instant**) a :

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R^a : sequence of statement nodes executed during a

- ▶ $len(R^a) = k(a)$ is length of a
- ▶ R^a is function mapping each **micro tick index** $1 \leq j \leq k(a)$ to node $R^a(j) = c_j^a.node$ executed at index j

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- ▶ all macro tick configurations are connected by clock steps, i.e., $(C_{k(a)}^a, M_{k(a)}^a) \rightarrow_{tick} (C_0^{a+1}, M_0^{a+1})$

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- ▶ initial continuation pool $C_0^0 = \{c_0\}$ activates the entry node of the G 's Root thread, i.e., $c_0.node = Root.en$ and $c_0.status = active$
- ▶ all macro tick configurations are connected by clock steps, i.e., $(C_{k(a)}^a, M_{k(a)}^a) \rightarrow_{tick} (C_0^{a+1}, M_0^{a+1})$

Trace: externally visible output values at each macro tick R [TR, Sec. 3.9]

Determinacy

Recall:

$$(C_0^a, M_0^a) \xrightarrow{\gamma_{\mu s}^{c_1^a}} (C_1^a, M_1^a) \xrightarrow{\gamma_{\mu s}^{c_2^a}} \dots \xrightarrow{\gamma_{\mu s}^{c_{k(a)}^a}} (C_{k(a)}^a, M_{k(a)}^a) \quad (1)$$

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- ▶ **Suffices to ensure that sequence of macro ticks \Longrightarrow is determinate**
- ▶ Micro tick behavior $\rightarrow_{\mu S}$ may well be non-determinate

Active and Pausing Continuations are Concurrent [TR, Prop. 2]

Given:

- ▶ (C, M) , reachable (micro or macro tick) configuration
- ▶ $c_1, c_2 \in C$, active or pausing continuations with $c_1 \neq c_2$

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Then:

- ▶ $c_1.node \neq c_2.node$
- ▶ $th(c_1.node) \parallel th(c_2.node)$
- ▶ No instantaneous sequential path from $c_1.node$ to $c_2.node$ or vice versa

(Proof: see [TR])

Concurrency vs. Sequentiality Revisited I

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- ▶ Thus, consider only run-time concurrent data dependencies

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Recall: Static concurrency $\not\Rightarrow$ run-time concurrency

- ▶ Consider Reinc example
- ▶ Thus, can ignore some statically concurrent data dependencies

Concurrency vs. Sequentiality Revisited II

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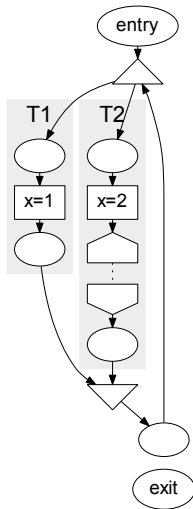
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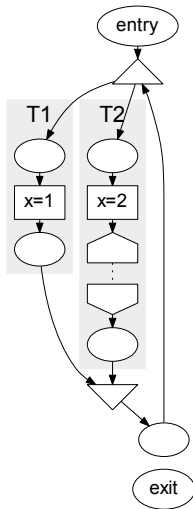
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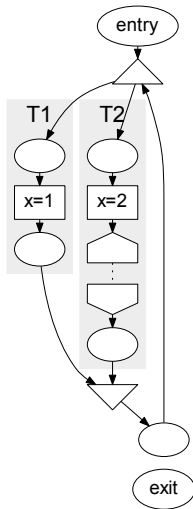
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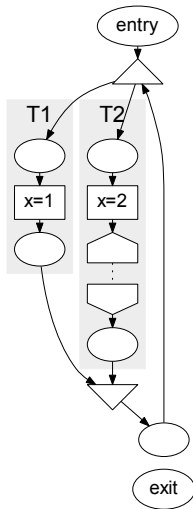
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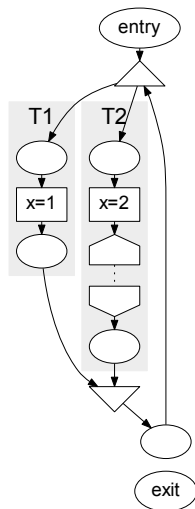
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Thus, concurrency and (static) sequentiality are not **mutually exclusive**, but **orthogonal**!



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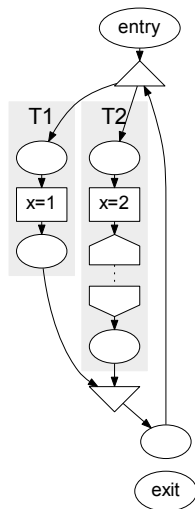
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- ▶ Assignments to x sequentially ordered? Yes!

Thus, concurrency and (static) sequentiality are not **mutually exclusive, but orthogonal!**

However, (instantaneous) *run-time* sequentiality (on node *instances*) does exclude run-time concurrency



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- ▶ Like the synchronous MoC, the SC MoC ensures macro-tick determinacy by inducing certain scheduling constraints on variable accesses
- ▶ **Unlike** the synchronous MoC, the SC MoC tries to take **maximal advantage of the execution order already expressed by the programmer** through sequential commands
- ▶ A scheduler can only affect the order of variable accesses through **concurrent** threads

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Similarly, threads are not concurrent with parent thread

- ▶ Because of path ordering \prec , a parent thread is always suspended when a child thread is in operation
- ▶ Thus, not up to scheduler to decide between parent and child thread
- ▶ No race conditions between variable accesses performed by parent and child threads; no source of non-determinacy

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In the following, will define such a restriction:
the SC-admissible schedules

Guideline for SC-admissibility

- ▶ Initialize-Update-Read protocol, for concurrent accesses
- ▶ Want to conservatively extend Esterel's "Write-Read protocol" (must do emit *before* testing)
- ▶ But does Esterel *always* follow write-read protocol?

Write After Read Revisited

```
module WriteAfterRead
output x, y, z;

emit x;
[
  present x then
    emit y
  end
||
  present y then
    emit z
  end;
  emit x
]
end
```

Esterel version

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Esterel version

```
module WriteAfterRead
output int x, y, z;
{
  x = 1;
  fork
    y = x;
  par
    z = y;
    x = 1;
  join
}
```

SCL version

Write After Read Revisited

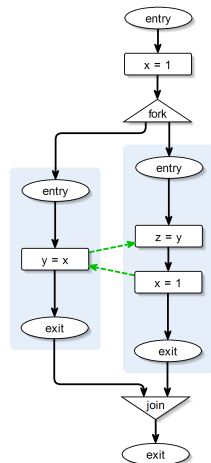
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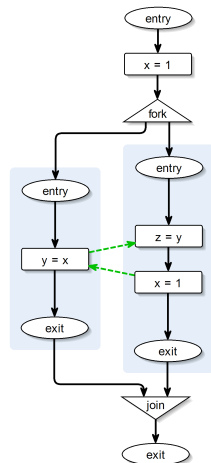
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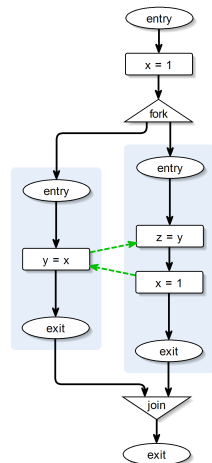
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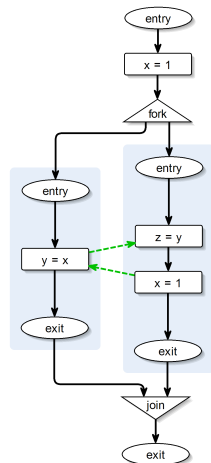
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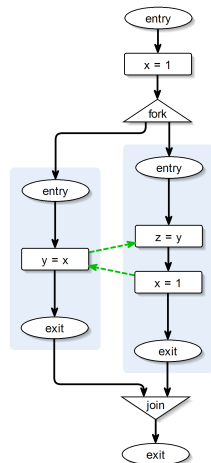
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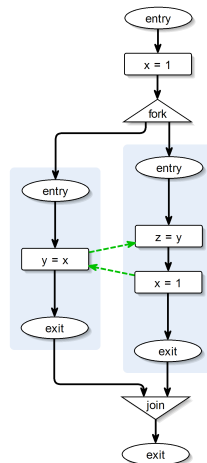
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- ▶ **One approach:** permit concurrent ineffective writes after read

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- ▶ Both schedules would be permitted under a scheduling regime that permits ineffective writes
- ▶ \rightarrow Strengthen notion of “ineffective writes”:
- ▶ Consider writes “ineffective” only if they do not change read!

Ineffectiveness – 2nd Try

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```
1 module InEffective2
2 output bool x = false;
3   int y;
4   {
5     fork
6       if (!x) {
7         y = 1;
8         x = x xor true
9       }
10      else
11        y = 0
12    par
13      x = x xor true;
14    join
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- ▶ → Replace “ineffectiveness” by “confluence”

Overview

Motivation

Formalizing Sequential Constructiveness (SC)

The SC Language (SCL) and the SC Graph (SCG) [Sec. 2]

Free Scheduling of SCGs [Sec. 3]

The SC Model of Computation [Sec. 4]

Wrap-Up

Combination Functions [Def. 4.1]

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Given:

- ▶ Valid configuration (C, M) of SCG
- ▶ Nodes $n_1, n_2 \in N$

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Observations I

- ▶ Confluence is taken *relative* to valid configurations (C, M) and *indirectly* as the absence of conflicts
- ▶ Instead of requiring that confluent nodes commute with each other for *arbitrary* memories, we only consider those configurations (C', M') that are *reachable* from (C, M)
- ▶ *E. g.*, if it happens for a given program that in all memories M' reachable from a configuration (C, M) two expressions ex_1 and ex_2 evaluate to the same value, then the assignments $x = ex_1$ and $x = ex_2$ are confluent in (C, M)

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- ▶ Similarly, if the two assignments are never jointly active in any reachable continuation pool C' , they are confluent in (C, M) , too
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- ▶ Thus, statements may be confluent for some program relative to some reachable configuration, but not for other configurations or in another program
- ▶ However, notice that relative writes of the same type are confluent in the absolute sense, *i. e.*, for all valid configurations (C, M) of all programs

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- ▶ Confluence $n_1 \sim_{(C,M)} n_2$ requires conflict-freeness for *all* configurations (C', M') reachable from (C, M) by *arbitrary* micro-sequences under *free scheduling*
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- ▶ Exploit this in following definition of confluence of *node instances* by making confluence of node instances within a macro tick relative to the index position at which they occur

Confluence of Node Instances [Def. 4.5]

Given:

- ▶ Macro tick R
- ▶ (C_i, M_i) for $0 \leq i \leq \text{len}(R)$, the configurations of R
- ▶ Node instances $ni_1 = (n_1, i_1)$ and $ni_2 = (n_2, i_2)$ in R

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- ▶ for $i = \min(i_1, i_2) - 1$
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- ▶ Q: Is L13 ineffective *relative to L6*?

InEffective2 Revisited

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1 module InEffective2
2 output bool x = false;
3   int y;
4   {
5     fork
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→ Def. of SC-admissibility – specifically, the underlying scheduling relations – uses confluence condition

Scheduling Relations [Def 4.6]

Given:

- ▶ Macro tick R with
- ▶ Node instances $ni_{1,2} = (n_{1,2}, i_{1,2})$, i. e., $1 \leq i_{1,2} \leq \text{len}(R)$ and $n_{1,2} = R(i_{1,2})$
- ▶ $ni_{1,2}$ concurrent in R , i. e., $ni_1 \mid_R ni_2$
- ▶ $ni_{1,2}$ not confluent in R , i. e., $ni_1 \not\sim_R ni_2$

Then:

- ▶ $ni_1 \rightarrow_\alpha^R ni_2$ iff $n_1 \rightarrow_\alpha n_2$ for some $\alpha \in \alpha_{iur}$
- ▶ $ni_1 \rightarrow^R ni_2$ iff $i_1 < i_2$; i. e., ni_1 happens before ni_2 in R .

Sequential Admissibility [Def. 4.7]

A macro tick R is **SC-admissible** iff

- ▶ for all node instances $ni_{1,2} = (n_{1,2}, i_{1,2})$ in R , with $1 \leq i_{1,2} \leq \text{len}(R)$ and $n_{1,2} = R(i_{1,2})$,
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the **scheduling condition** SC_α holds:

if $ni_1 \xrightarrow{\alpha}^R ni_2$ then $ni_1 \xrightarrow{R} ni_2$.

A run for an SCG is **SC-admissible** if all macro ticks R in this run are SC-admissible.

SC-admissibility vs. Determinacy

SC-admissibility vs. Determinacy

```
1  module NonDet
2  output bool x = false, y = false;
3  {
4  fork { // Thread CheckX
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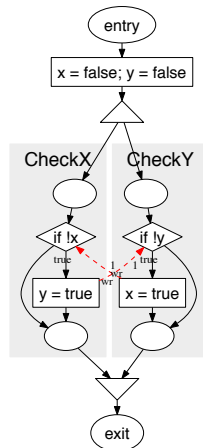
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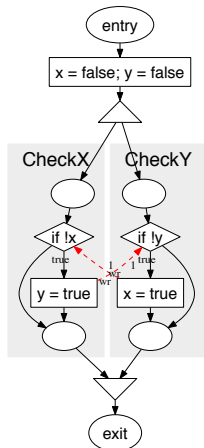
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Thus: **SC-admissibility** $\not\equiv$ **Determinacy**

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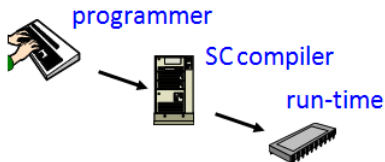
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Thus: **Determinacy** $\not\Rightarrow$ **SC-admissibility**

Sequential Constructiveness [Def. 4.8]



Definition: A program P is **sequentially constructive (SC)** iff for each initial configuration and input sequence:

1. There exists an SC-admissible run (P is **reactive**)
2. Every SC-admissible run generates the same determinate sequence of macro responses (P is **determinate**)

Overview

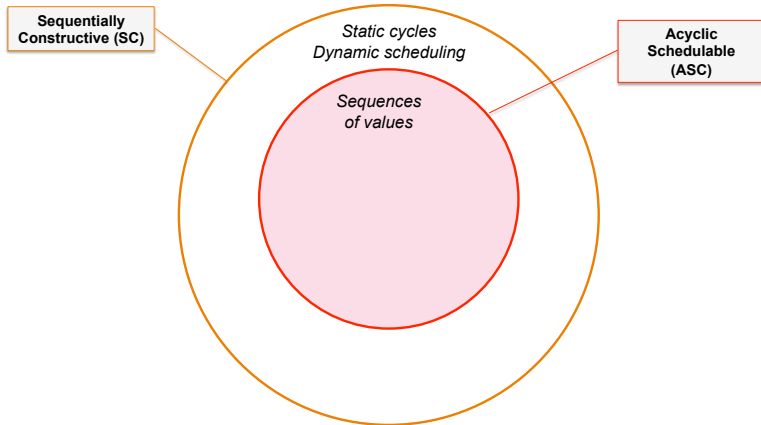
Motivation

Formalizing Sequential Constructiveness (SC)

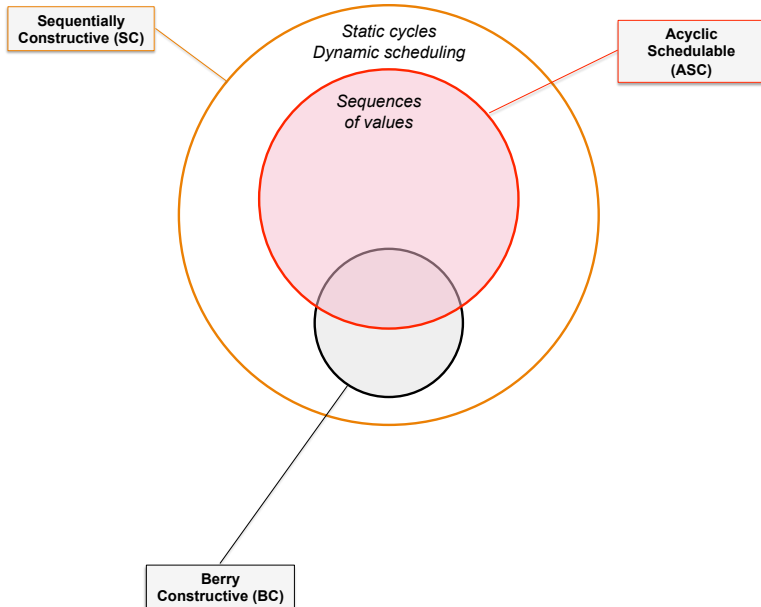
Wrap-Up

Synchronous Program Classes
Summary

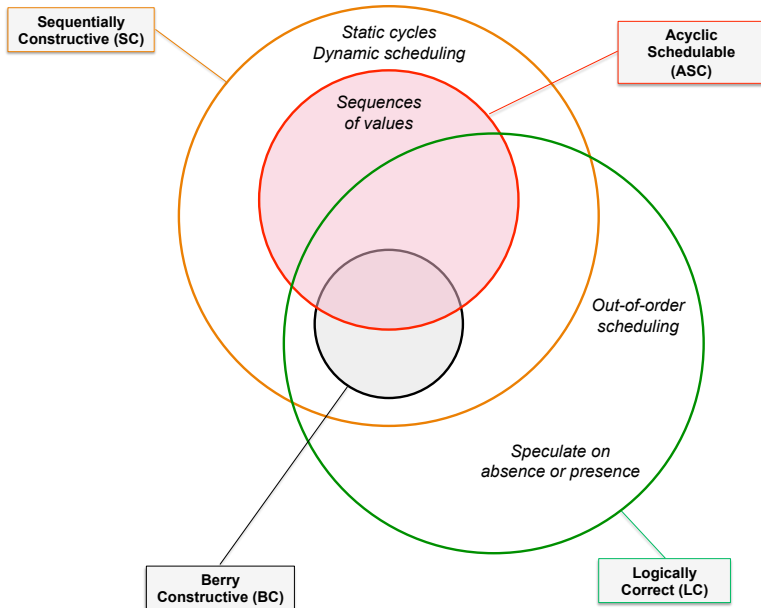
Synchronous Program Classes [TR, Sec. 9]



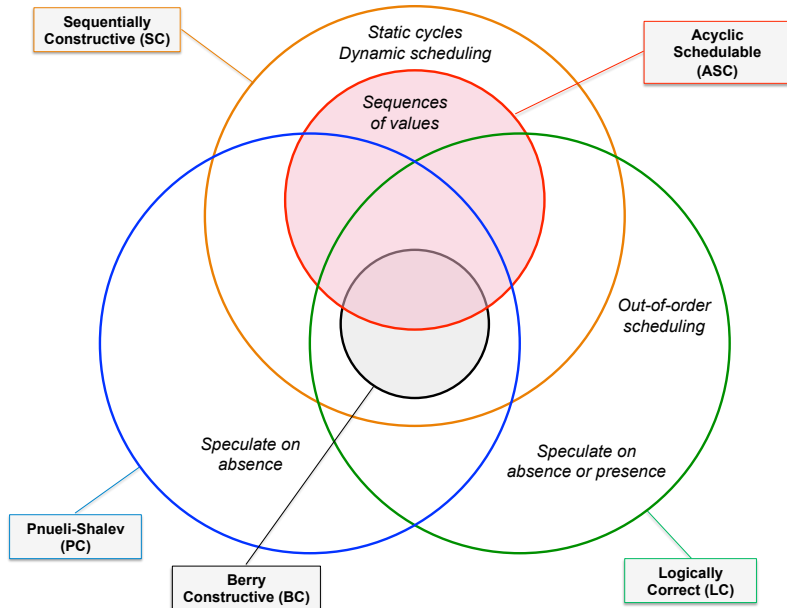
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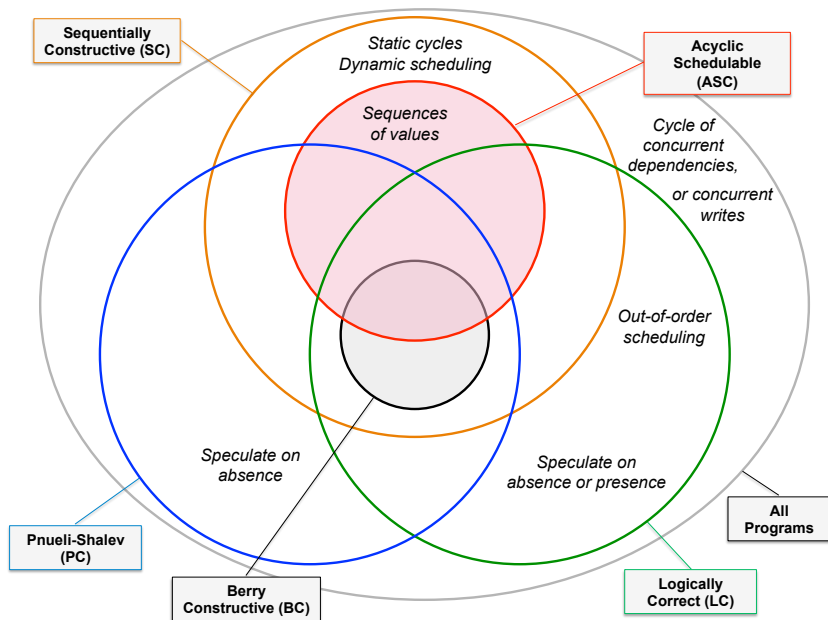
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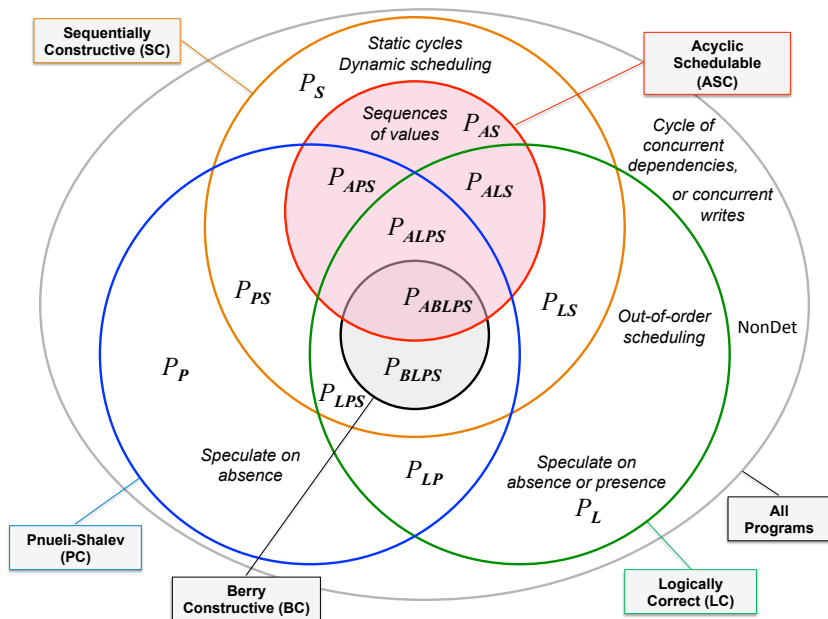
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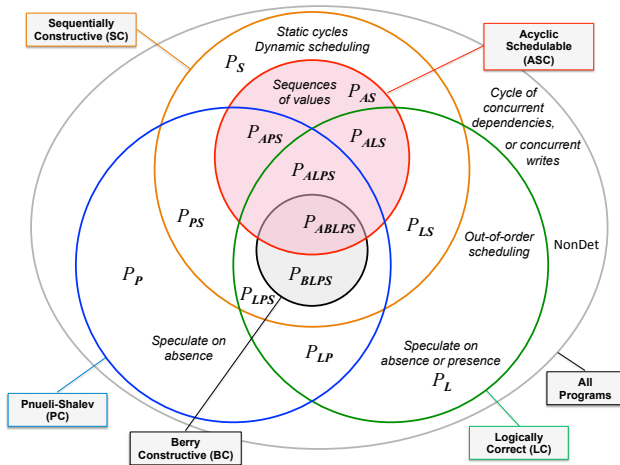
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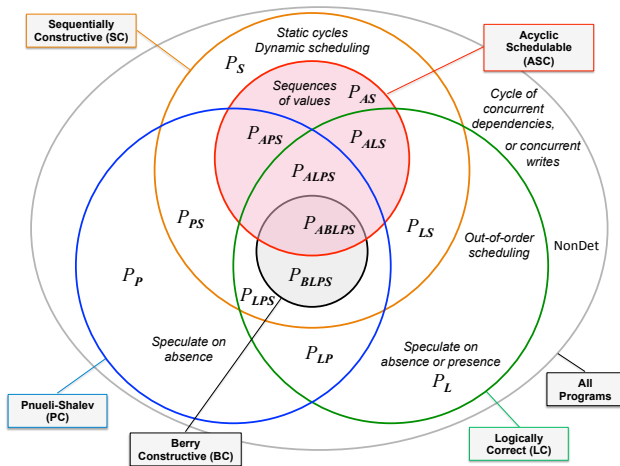


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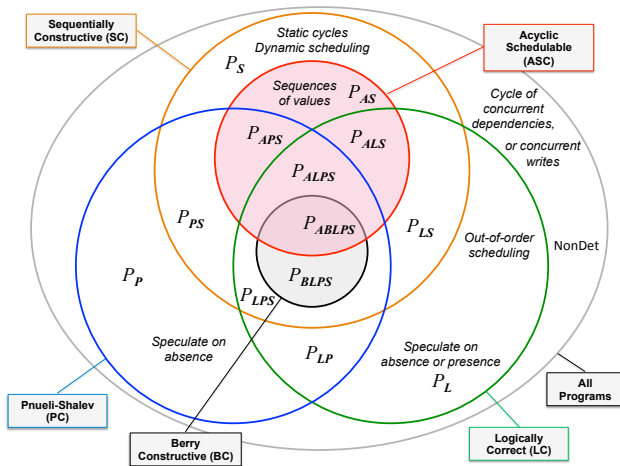
Example $P_{AS} =$

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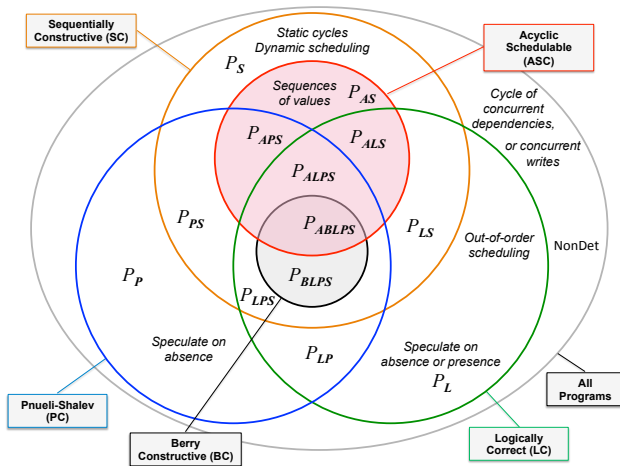
Example $P_{AS} = \text{if } (!x) x = 1$

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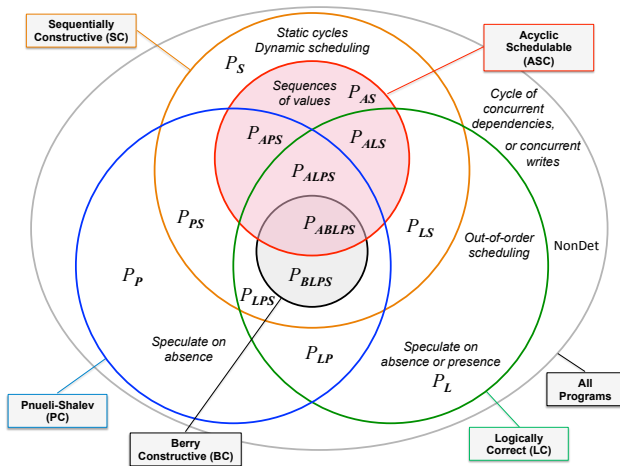
Example $P_{ALS} =$

Synchronous Program Classes



Example $P_{ALPS} =$

Synchronous Program Classes



Example $P_{ALPS} = \text{if } (!x \ \&\& \ y) \ \{x = 1; \ y = 1\}$

Summary

Underlying idea of sequential constructiveness rather simple

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- ▶ Prescriptive instead of descriptive sequentiality
- ▶ Thus circumventing “spurious” causality problems
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- ▶ Prescriptive instead of descriptive sequentiality
- ▶ Thus circumventing “spurious” causality problems
- ▶ Initialize-update-read protocol

However, precise definition of SC MoC not trivial

- ▶ Challenging to ensure conservativeness relative to Berry-constructiveness
- ▶ Plain initialize-update-read protocol does not accomodate, *e. g.*, signal re-emissions
- ▶ Restricting attention to *concurrent, non-confluent* node instances is key

Conclusions

- ▶ Clocked, **synchronous model of execution** for **imperative, shared-memory multi-threading**
- ▶ Conservatively extends synchronous programming (Esterel) by **standard sequential control flow** (Java, C)
- ▶ \implies Deterministic concurrency with synchronous foundations, but without synchronous restrictions
 - ▶ 😊 Expressive and intuitive sequential paradigm
 - ▶ 😊 Predictable concurrent threads

Future Work

Plenty of extensions/adaptations possible . . .

- ▶ Alternative notions of sequential constructiveness:
 - ▶ A truly “constructive” approach that sharpens SC admissibility to determinate schedules
 - ▶ Extension of iur-protocol, e. g., to model ForeC
- ▶ Improved synthesis & analysis — see also next lecture