Synchronous Languages—Lecture 06

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Esterel IV—The Constructive Semantics

The 5-Minute Review Session

- 1. What is the *state* of an Esterel program? Which implementation alternatives are there to memorize state?
- 2. What are implementation alternatives to interface with the environment, *e. g.*, a device that can be on or off?
- 3. What is the relationship between events and states?
- 4. What are possible examples for *causality problems*? What is the reason for these problems?
- 5. When is an Esterel program *logically reactive*? ... correct?

Overview

The Constructive Semantics

External Justification vs. Self-Justification The Constructive Behavioral Semantics The Constructive Operational Semantics

Programming in Esterel:

- Analyze input events to generate appropriate output signals
- Use concurrent statements and intermediate local signals to create modular, well-structured programs

Natural way of thinking:

Information propagation by cause and effect



```
module P1:
input I;
output 0;
signal S1, S2 in
  present I then emit S1 end
||
  present S1 else emit S2 end
||
  present S2 then emit 0 end
end signal
end module
```

Is this logically correct?

Yes!

Is this well-behaved wrt information propagation?

Yes!

```
module P9:
[
    present 01 then emit 01 end
]
present 01 then
    present 02 else emit 02 end
end
]
```

Is this logically correct?

Yes!

Is this well-behaved wrt information propagation?

► No!

- Accepting P9 as correct is
 - Logically possible
 - But against (imperative) intention of the language

"present S then p end":

- First test the status of S, then execute p if S is present
- Status of S should not depend on what p might do
- Synchrony hypothesis:
 - Ordering implicit in the then word is not that of time, but that of sequential causality
- Want actual computation:
 - "Since S is present, we take the then branch"
- Don't want speculative computation:
 - "If we assume S present, then we take the then branch"

- Aside from the explicit concurrency "||", all Esterel statements are sequential
- Want to preserve this in the semantics



- This is logically correct
- But still want to reject it:
 - In the logical semantics, the information that 0 is present flows backwards across the sequencing operator
 - Contradicts basic intuition about sequential execution

The Constructive Semantics

Constructive semantics:

Does not check assumptions about signal statuses

Instead, propagates facts about control flow and signal statuses

Three equivalent presentations:

- 1. Constructive behavioral semantics
- 2. Constructive operational semantics
- 3. Circuit semantics

The Constructive Semantics

- 1. Constructive behavioral semantics:
 - Derived from the logical behavioral semantics
 - Adds constructive restrictions to logical coherence rule
 - Is the simplest way of defining the language
- 2. Constructive operational semantics:
 - Based on an interpretation scheme expressed by term rewriting rules defining microstep sequences
 - Is the simplest way of defining an efficient interpreter
- 3. Circuit semantics:
 - Translation of programs into constructive circuits
 - Is the core of the Esterel v5 compiler

- ... retains the spirit of the logical coherence semantics
- ...adds reasoning about what a program must or cannot do
- Define disjoint predicates to express
 - "A statement must terminate, must pause, must exit a trap T, or must emit a signal S"
 - "A statement cannot terminate, cannot pause, cannot exit a trap T, or cannot emit a signal S"
- The Must (Cannot) predicate determines
 - Which signals are present (absent)
 - Which statements are (cannot be) executed

Recall: Logical Coherence Law

A signal S is present in an instant iff an "emit S" statement is executed in this instant.

Replace with disjoint Constructive Coherence Laws:

A signal S is present iff an "emit S" statement must be executed. A signal S is absent iff an "emit S" statement cannot be executed

- Define *Must* and *Cannot* predicates by structural induction on statements
- A signal can have three statuses:
 - "+": known to be present
 - ▶ "—": known to be absent
 - "⊥": yet unknown
- Is technically easier to define the Cannot predicate as the negation of a Can predicate
 - No constructiveness problem here as we only deal with finite sets

p;q (Sequence)

► Must (resp. can) execute *q* if *p* must (resp. can) terminate

present S then p else q end (Test)

▶ If *S* is known to be present:

Test behaves as p

- ▶ If *S* is known to be absent:
 - Test behaves as q
- ▶ If *S* is yet unknown:
 - Test can do whatever p or q can do
 - There is nothing the test must do. In particular, it does not even have to do what both p and q have to do—this is the essence of disallowing speculative execution.

- Main novelty is in analysis of output and local signals
- Consider local signal here; output signal is similar
- signal S in p end (Local signal)
 Can predicate:
 - Recursively analyze p with status \perp for S

signal S in p end (Local signal) Must predicate:

- Assume we already know that we must execute signal S in p end in some signal context E
- Must compute final status of S to determine signal context of p
- First analyze p in E augmented by setting the unknown status ⊥ for S
- If S must be emitted:
 - Propagate this information by reanalyzing p in E with S present
 - This may generate more information about the other signals
- Similarly, if we find that *S* cannot be emitted:
 - Reanalyze *p* in *E* with *S* absent

Accepting Programs

CAU

In the constructive behavioral semantics, a program is accepted as constructive iff fact propagation using the *Must* and *Can* (or *Cannot*) predicates suffices in establishing presence or absence of all output signals (and we can also compute a derivative—see later)

```
module P1:
input I;
output 0;
signal S1, S2 in
present I then emit S1 end
||
present S1 else emit S2 end
||
present S2 then emit 0 end
end signal
end module
```

Accepting Programs

CAU



- Can analyze this with just propagating facts
 - No need for speculative computation based on assumptions
 - Our analysis still "looks ahead" to see what must/cannot be done, but always builds on facts established so far, not on speculations

However, analysis involves recomputations

Avoiding this is goal of operational and circuit semantics!

If the must and cannot predicates bring no information about the status of some signal:

Programs is rejected

```
module P3:
output 0;
present 0 else emit 0 end
end module
```

```
module P4:
output 0;
present 0 then emit 0 end
end module
```



- Constructiveness => logical correctness
- But not vice versa!

```
module P9:
[
   present 01 then emit 01 end
]
   present 01 then
    present 02 else emit 02 end
   end
]
```

- Both 01 and 02 can be emitted
- No signal must be emitted
- No progress—reject P9!

Consider variant of P2:



Are not allowed to speculatively execute branches

Again no progress—reject P11!



- Must reject P12 as well!
- Does an equivalent HW-circuit always stabilize? (Will come back to this later ...)

The Must, Cannot, and Can Functions

- Must function determines what must be done in a reaction $P \xrightarrow[l]{O} P'$
- Has the form $Must(p, E) = \langle S, K \rangle$
 - ▶ *E*: partial event, associating status in $B_{\perp} = \{+, -, \bot\}$ with each signal
 - S: set of signals that p must emit
 - K: set of completion codes that p must return

Is either empty or a singleton

- Use subscripts to access elements of result pair:
 - $Must(p, E) = \langle Must_s(p, E), Must_k(p, E) \rangle$

The Must, Cannot, and Can Functions

- Cannot^m function prunes out false paths
- $Cannot^m(p, E) = \langle Cannot^m_s(p, E), Cannot^m_k(p, E) \rangle = \langle S, K \rangle$
- Extra argument m ∈ {+, ⊥} indicates whether it is known that p must be executed in event E
- Can^m(p, E) is component-wise complement

Completion and signal emission:

$$Must(k, E) = Can^{m}(k, E) = \langle \emptyset, \{k\} \rangle$$
$$Must(!s, E) = Can^{m}(!s, E) = \langle \{s\}, \{0\} \rangle$$

Suspension:

$$Must(s \supset p, E) = Must(p, E)$$

 $Can^{m}(s \supset p, E) = Can^{m}(p, E)$



► Signal test:

CAU

$$Must((s?p,q),E) = egin{cases} Must(p,E) & ext{if } s^+ \in E \ Must(q,E) & ext{if } s^- \in E \ \langle \emptyset, \emptyset
angle & ext{if } s^\perp \in E \end{cases}$$

$$Can^{m}((s?p,q),E) = egin{cases} Can^{m}(p,E) & ext{if } s^{+} \in E \ Can^{m}(q,E) & ext{if } s^{-} \in E \ Can^{\perp}(p,E) \cup Can^{\perp}(q,E) & ext{if } s^{\perp} \in E \end{cases}$$

Sequencing:

$$Must(p; q, E) = \begin{cases} Must(p, E) \\ \text{if } 0 \notin Must_k(p, E) \\ \langle Must_S(p, E) \cup Must_S(q, E), Must_k(q, E) \rangle \\ \text{if } 0 \in Must_k(p, E) \end{cases}$$

$$Can^{m}(p;q,E) = \begin{cases} Can^{m}(p,E) \\ \text{if } 0 \notin Can_{k}^{m}(p,E) \\ \langle Can_{S}^{m}(p,E) \cup Can_{S}^{m'}(q,E), Can_{k}^{m}(p,E) \setminus 0 \cup Can_{k}^{m'}(q,E) \rangle \\ \text{if } 0 \in Can_{k}^{m}(p,E) \\ \text{with } m' = \begin{cases} + \text{ if } m = + \land 0 \in Must_{k}(p,E) \\ \bot \text{ otherwise} \end{cases}$$

Local signal declaration:

$$Must(p \setminus s, E) = \begin{cases} Must(p, E * s^{+}) \setminus s & \text{if } s \in Must_{S}(p, E * s^{\perp}) \\ Must(p, E * s^{-}) \setminus s & \text{if } s \notin Can_{S}^{+}(p, E * s^{\perp}) \\ Must(p, E * s^{\perp}) \setminus s & \text{otherwise} \end{cases}$$

$$Can^{m}(p \setminus s, E) = \begin{cases} Can^{+}(p, E * s^{+}) \setminus s \\ \text{if } m = + \text{ and } s \in Must_{S}(p, E * s^{\perp}) \\ Can^{m}(p, E * s^{-}) \setminus s \\ \text{if } s \notin Can^{+}_{S}(p, E * s^{\perp}) \\ Can^{m}(p, E * s^{\perp}) \setminus s \\ \text{otherwise} \end{cases}$$

- Note the Can/Must asymmetry: in the Can-predicate of the local signal declaration, check for m = + before calling Must to avoid speculative computation
- Otherwise, would accept program

```
present 0 then
  signal S in
  emit S
  ||
   present S else emit 0 end
  end
end
```



Loop:

$$Must(p*, E) = Must(p, E)$$

 $Can^m(p*, E) = Can^m(p, E)$

Parallel:

$$Must(p|q, E) = \langle Must_S(p, E) \cup Must_S(q, E), Max(Must_k(p, E), Must_k(q, E)) \rangle$$

$$Can^{m}(p|q, E) = \langle Can^{m}_{S}(p, E) \cup Can^{m}_{S}(q, E), Max(Can^{m}_{k}(p, E), Can^{m}_{k}(q, E)) \rangle$$

The Max-operator on sets of completion codes is defined as

$$Max(K,L) = \begin{cases} \emptyset & \text{if } K = \emptyset \text{ or } L = \emptyset \\ \{\max(k,l) \mid k \in K, l \in L\} & \text{if } K, L \neq \emptyset \end{cases}$$

► Trap:

$$Must(\{p\}, E) = \langle Must_{S}(p, E), \downarrow Must_{k}(p, E) \rangle$$
$$Can^{m}(\{p\}, E) = \langle Can_{S}^{m}(p, E), \downarrow Can_{k}^{m}(p, E) \rangle$$

Shift:

$$Must(\uparrow p, E) = \langle Must_{S}(p, E), \uparrow Must_{k}(p, E) \rangle$$
$$Can^{m}(\uparrow p, E) = \langle Can^{m}_{S}(p, E), \uparrow Can^{m}_{k}(p, E) \rangle$$

Definition of the Constructive Behavioral Semantics

The constructive behavioral semantics of a given program is defined by a two-step procedure, yielding the current reaction and the derivative:

- 1. Compute output event *O* using *Must* and *Cannot* predicates
 - This fails if status of some output signal cannot be determined to be + or -
- 2. Compute behavioral transition yielding program derivative
 - This fails if body of some loop is found to terminate instantaneously
 - This also fails if we cannot establish the presence/absence of a local signal

Definition of the Constructive Semantics

Step 1: Compute output event *O* Approach:

- ▶ Start with undefined *O* (all output signal statuses = \perp)
- Iteratively enrich O using Must and Can information

Terminate when this stabilizes (guaranteed by monotonicity)
 Formalize this as computation of a least fixed point (see draft book)

Algorithm to Compute Outputs

```
function computeOut(P, I)

E = I \cup \{s^{\perp} \mid s \in Out(P)\}
do

E' = E
can = Can_{S}^{+}(P, E)
must = Must_{S}(P, E)
E = I \cup \{s^{+} \mid s \in must\}
\cup \{s^{-} \mid s \in Out(P) \setminus can\}
\cup \{s^{\perp} \mid s \in can \setminus must\}
while (E' \neq E)

if \exists s : s^{\perp} \in E then error ("not constructive")

return E
```

Example for *Can* analysis

Consider the program p = !S; S?!O, 1 and environment $\{S^{\perp}, O^{\perp}\}$.

$$Can^{+}(!S, \{S^{\perp}, O^{\perp}\}) = \langle \{S\}, \{0\} \rangle$$

$$Must_{k}(!S, \{S^{\perp}, O^{\perp}\}) = \{0\}$$

$$Can^{\perp}(!O, \{S^{\perp}, O^{\perp}\}) = \langle \{O\}, \{0\} \rangle$$

$$Can^{\perp}(1, \{S^{\perp}, O^{\perp}\}) = \langle \emptyset, \{1\} \rangle$$

$$Can^{+}(S?!O, 1, \{S^{\perp}, O^{\perp}\}) = \langle \{O\}, \{0, 1\} \rangle$$

$$Can^{+}(!S; S?!O, 1, \{S^{\perp}, O^{\perp}\}) = \langle \{S, O\}, \{0, 1\} \rangle$$

Gives no new information on signal status

Example for *Must* analysis

Consider the program p = !S; S?!O, 1 and environment $\{S^{\perp}, O^{\perp}\}$

1.
$$\begin{aligned} & \textit{Must}(!S, \{S^{\perp}, O^{\perp}\}) = \langle \{S\}, \{0\} \rangle \\ & \textit{Must}(S?!O, 1, \{S^{\perp}, O^{\perp}\}) = \langle \emptyset, \emptyset \rangle \\ & \textit{Must}(!S; S?!O, 1, \{S^{\perp}, O^{\perp}\}) = \langle \{S\}, \emptyset \rangle \end{aligned}$$

2. Update environment to $\{S^+, O^{\perp}\}$

3.
$$\begin{aligned} Must(!S, \{S^+, O^{\perp}\}) &= \langle \{S\}, \{0\} \rangle \\ Must(!O, \{S^+, O^{\perp}\}) &= \langle \{O\}, \{0\} \rangle \\ Must(S?!O, 1, \{S^+, O^{\perp}\}) &= \langle \{O\}, \{0\} \rangle \\ Must(!S; S?!O, 1, \{S^+, O^{\perp}\}) &= \langle \{S, O\}, \{0\} \rangle \end{aligned}$$

- 4. Update environment to $\{S^+, O^+\}$
- 5. All signals have a defined status \rightarrow done

Definition of the Constructive Semantics

Step 2: Compute transition Rules are exactly as for logical behavioral semantics—except for changed rules for local signals

$$\frac{p \xrightarrow{E' * s^+, k} p' \quad S(E') = S(E) \setminus s}{p \setminus s \xrightarrow{E', k} p' \setminus s}$$
(sig +)

is replaced with

$$\frac{s \in \textit{Must}_s(p, E * s^{\perp}) \quad p \xrightarrow{E' * s^+, k} p' \quad S(E') = S(E) \setminus s}{p \setminus s \xrightarrow{E', k} p' \setminus s}$$

(csig +)

Definition of the Constructive Semantics

$$\frac{p \xrightarrow{E' * s^-, k} p' \quad S(E') = S(E) \setminus s}{p \setminus s \xrightarrow{E', k} p' \setminus s}$$
(sig -)

is replaced with

$$\frac{s \in Cannot_{s}^{+}(p, E * s^{\perp}) \quad p \xrightarrow{E' * s^{-}, k}_{E * s^{-}} p' \quad S(E') = S(E) \setminus s}{p \setminus s \xrightarrow{E', k}_{E} p' \setminus s}$$
(csig –)

- ... is defined by a rewriting-based interpretation scheme
 - \odot Instead of reasoning about what we must do, just do it
 - ② Formal definition and technical treatment of the constructive operational semantics is much heavier than that of the constructive behavioral semantics
- Will still take constructive behavioral semantics as the primary semantics

- Decorate signal declarations with status +, -, \perp
- Initially, all signals except inputs unknown
- Constructive operational semantics is a micro-step semantics
 - Current state indicated by •

Consider P1 with I present:

```
module P1:
input I<sup>+</sup>;
output 0<sup>⊥</sup>;
•signal S1<sup>⊥</sup>, S2<sup>⊥</sup> in
present I then emit S1 end
||
present S1 else emit S2 end
||
present S2 then emit 0 end
end signal
end module
```

Fork of the parallel statement:

```
module P1:
input I<sup>+</sup>;
output 0<sup>⊥</sup>;
signal S1<sup>⊥</sup>, S2<sup>⊥</sup> in
•present I then emit S1 end
||
•present S1 else emit S2 end
||
•present S2 then emit 0 end
end signal
end module
```

Only first thread can continue:

```
module P1:
input I<sup>+</sup>;
output 0<sup>⊥</sup>;
signal S1<sup>⊥</sup>, S2<sup>⊥</sup> in
present I then •emit S1 end
||
•present S1 else emit S2 end
||
•present S2 then emit 0 end
end signal
end module
```

Now emit S1:

```
module P1:
input I<sup>+</sup>;
output 0<sup>⊥</sup>;
signal S1<sup>+</sup>, S2<sup>⊥</sup> in
present I then emit S1 end•
||
•present S1 else emit S2 end
||
•present S2 then emit 0 end
end signal
end module
```

Now the 2nd branch can continue:

```
module P1:
input I<sup>+</sup>;
output 0<sup>⊥</sup>;
signal S1<sup>+</sup>, S2<sup>⊥</sup> in
present I then emit S1 end•
||
present S1 else emit S2 end•
||
•present S2 then emit 0 end
end signal
end module
```

Cannot emit S2 any more:

```
module P1:
input I<sup>+</sup>;
output 0<sup>⊥</sup>;
signal S1<sup>+</sup>, S2<sup>-</sup> in
present I then emit S1 end•
||
present S1 else emit S2 end•
||
•present S2 then emit 0 end
end signal
end module
```

Now 3rd branch can continue:

```
module P1:
input I<sup>+</sup>;
output 0<sup>⊥</sup>;
signal S1<sup>+</sup>, S2<sup>-</sup> in
present I then emit S1 end•
[]
present S1 else emit S2 end•
[]
present S2 then emit 0 end•
end signal
end module
```

Cannot emit 0 any more:

```
module P1:
input I<sup>+</sup>;
output 0<sup>-</sup>;
signal S1<sup>+</sup>, S2<sup>-</sup> in
present I then emit S1 end•
[]
present S1 else emit S2 end•
[]
present S2 then emit 0 end•
end signal
end module
```



Synchronize the terminated threads:

```
module P1:
input I<sup>+</sup>;
output 0<sup>-</sup>;
signal S1<sup>+</sup>, S2<sup>-</sup> in
present I then emit S1 end
||
present S1 else emit S2 end
||
present S2 then emit 0 end
end signal•
end module
```

Now consider P2:





After 3 microsteps:





Perform cannot analysis (as in constructive behavioral semantics)—and set 0 absent:



Take implicit else branch of test:





Statuses evolve monotonically

- Hence avoid most of the recomputations that take place in the constructive behavioral semantics
- Rejecting programs is similar to constructive behavioral semantics

```
module P3:
output 0;
present 0 else emit 0 end
end module
```

- No possible initial microstep \implies cannot set O^+
- ▶ Potential path to emit $0 \implies$ cannot set O^-

Signals:

- Signals are shared objects with status $\{+, -, \bot\}$
- Signal status initialization:
 - Input signals are initialized according to the input event
 - Other signals initialized to \perp
- Signal status changes:
 - Status of a signal S changes from \(\begin{aligned}
 blue to + as soon as an "emit S" statement is executed
 - Status of a signal S changes from ⊥ to − as soon as all the "emit S" statements have been found unreachable by the cannot false path analysis

Control:

- Sequential threads of control forked by parallel statements
- ▶ When a thread reaches a "present S" statement:
 - As long as the status of S is \perp :
 - Control remains there, frozen,
 - As soon as S has a non- \perp status:
 - Control can resume
- If several threads are enabled, any one of them can be chosen

Control:

- Threads are stopped by termination or by executing pause or exit statements
- Parallel statements synchronize stopped threads, as explained in the intuitive semantics
- Finally, the false path analysis explores all possible instantaneous paths towards emit statements
 - Takes into account all facts established so far
 - No speculative reasoning

Program Acceptance:

- Given an input, a program is accepted if the analysis succeeds in setting each signal status to a defined value + or -
- Logical correctness is guaranteed for accepted programs

To Go Further

 Albert Benveniste, Paul Caspi, Stephen A. Edwards, Nicolas Halbwachs, Paul Le Guernic, Robert De Simone, The synchronous languages 12 years later, *Proceedings of the IEEE*, Jan. 2003 vol. 91, issue 1, pages 64–83, http://citeseerx.ist.psu.edu/viewdoc/summary?doi= 10.1.1.96.1117